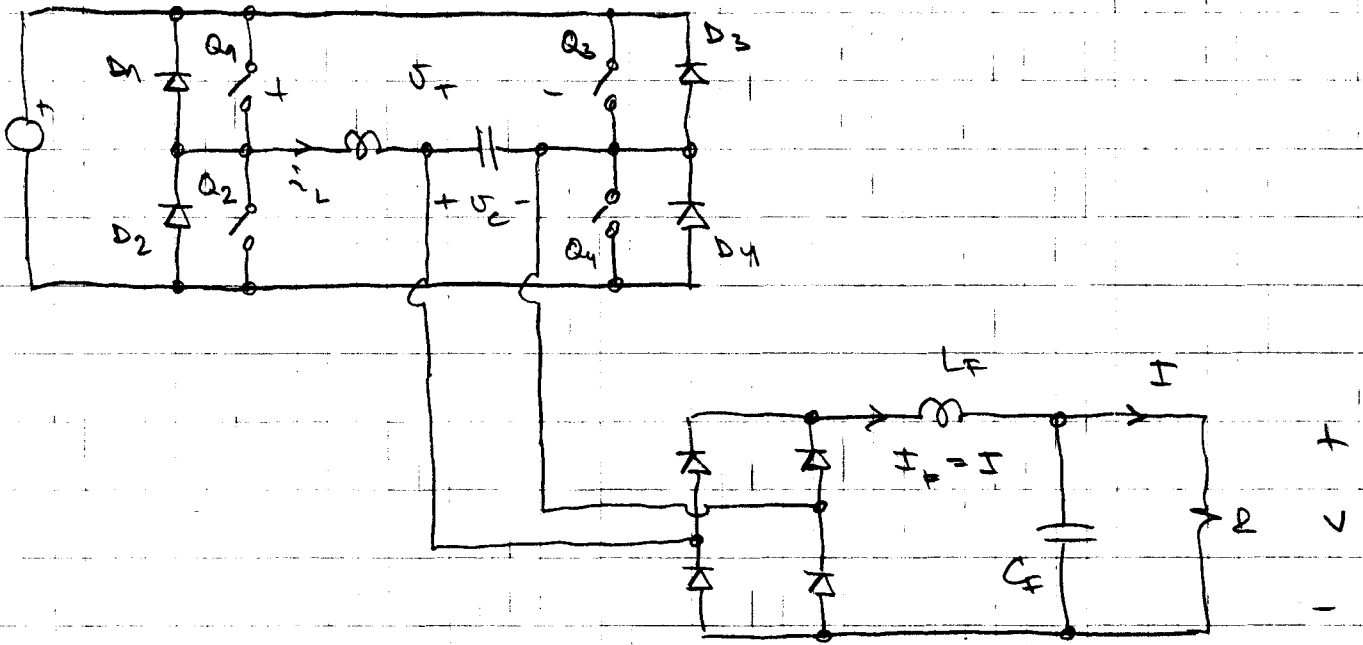


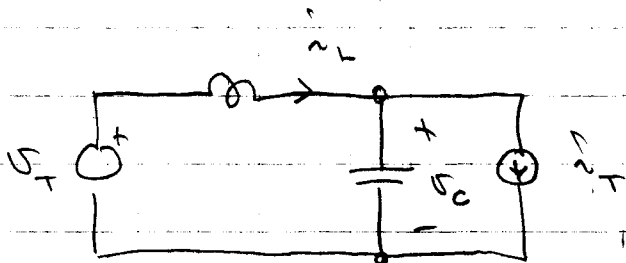
Различные Переходные Состояния



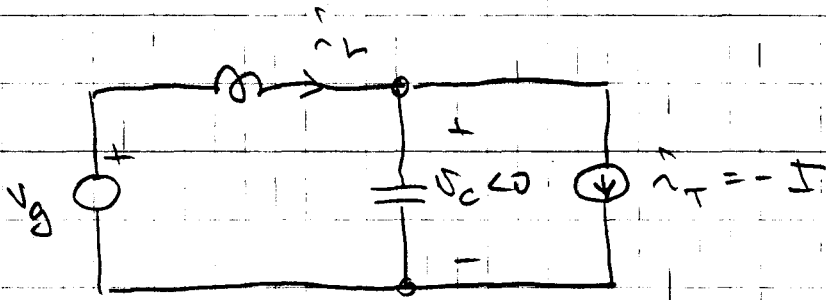
$$I_r = I$$

$$V = |U_c|$$

Interval	V_T	M_T	I_T	I_T	U_c
1	U_g	+1	-I	-I	-
2	U_g	+1	+I	+I	+
3	$-U_g$	-1	+I	+I	+
4	$-U_g$	-1	-I	-I	-

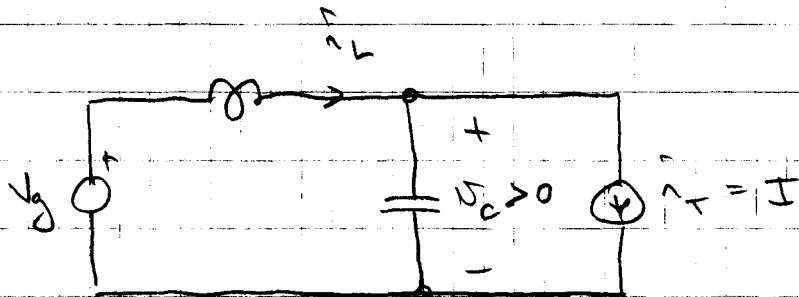


①



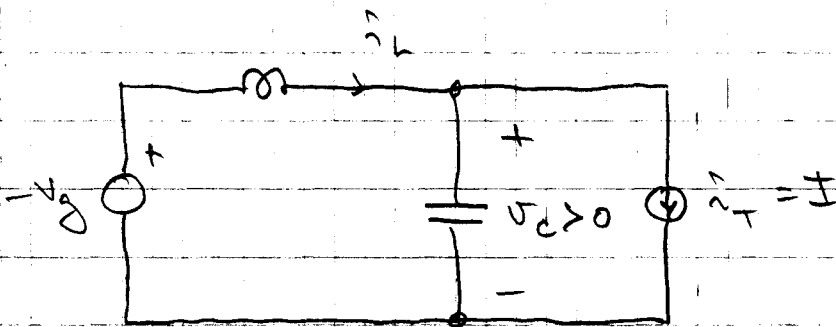
$Q1, Q4 / D1, D4$ $0 < \omega_0 t < \alpha$

②



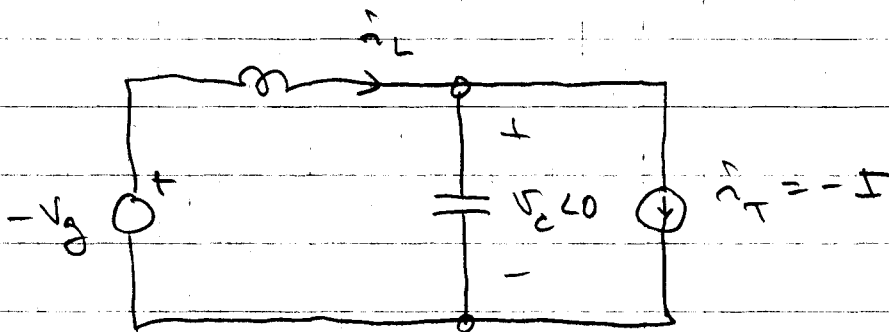
$Q1, Q4 / D1, D4$ $\alpha < \omega_0 t < \alpha + \beta = \beta$

③

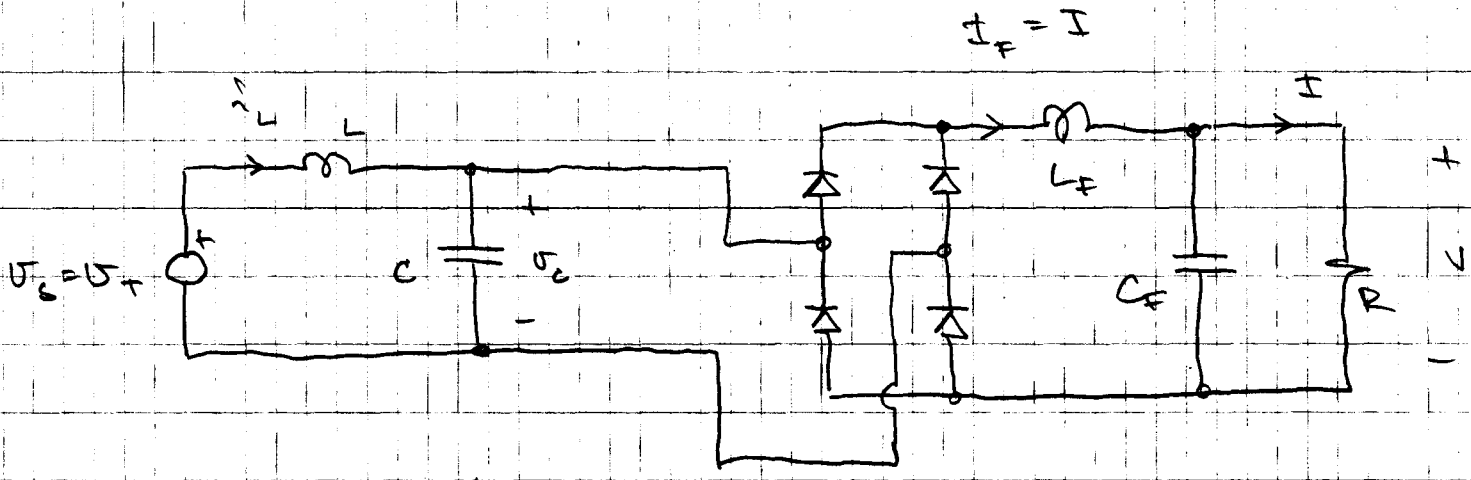


$Q2, Q3 / D2, D3$ $\beta < \omega_0 t < \beta + \alpha$

④



$Q2, Q3 / D2, D3$ $\beta + \alpha < \omega_0 t < 2\beta$



$$V = |U_c|$$

$$V = \frac{2}{T_s} \int_{t_a}^{t_a + \frac{1}{2} T_s} U_c(t) dt$$

$t = t_a$ - Beginn des ersten Spannungsimpulses U_c

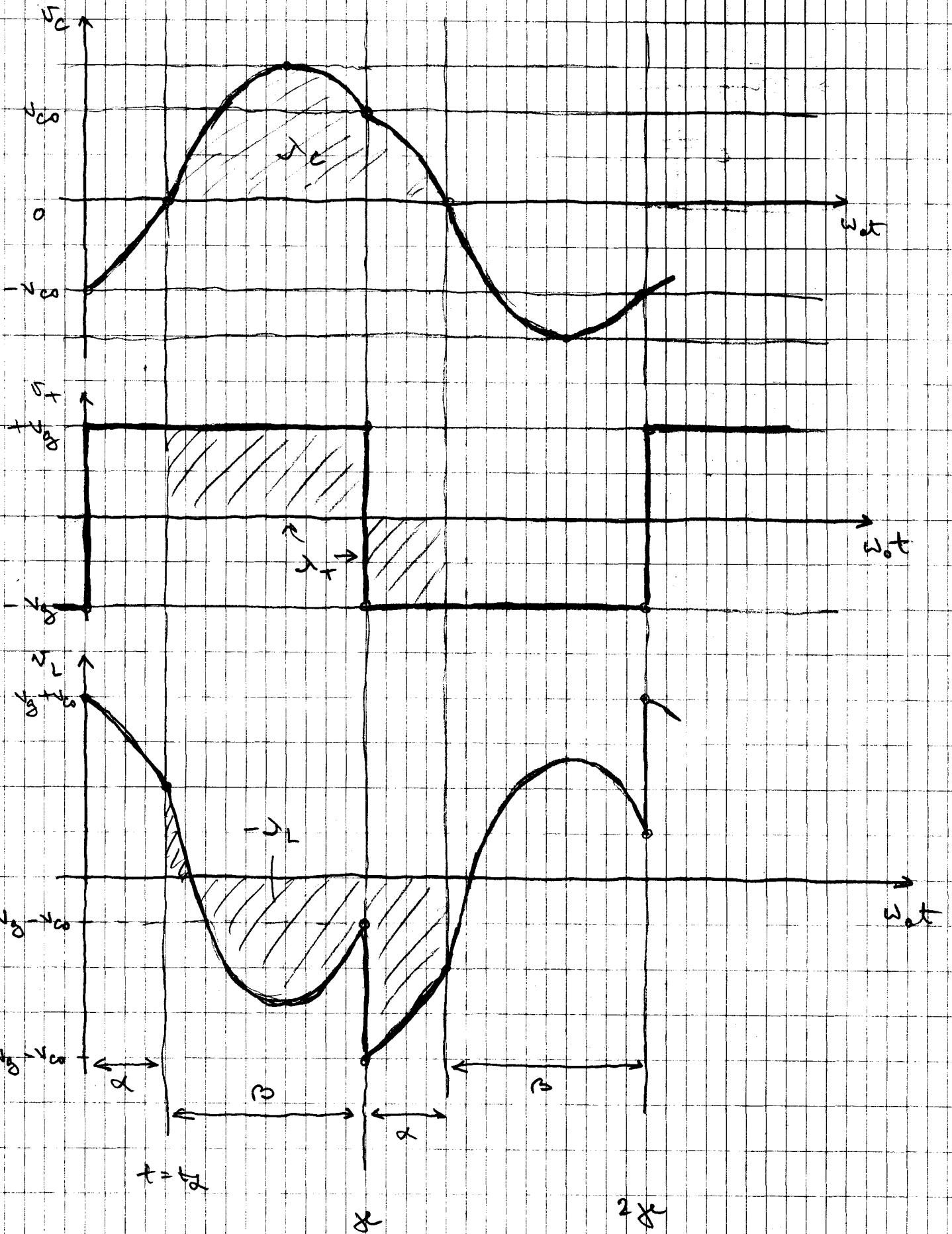
$$V = \frac{2}{T_s} J_c$$

$$J_c = \int_{t_a}^{t_a + \frac{1}{2} T_s} U_c(t) dt$$

$$J_c = J_T - J_L$$

$$J_T = \int_{t_a}^{t_a + \frac{1}{2} T_s} U_T(t) dt$$

$$J_L = \int_{t_a}^{t_a + \frac{1}{2} T_s} U_L(t) dt$$



$$V = \frac{2}{T_s} (\Delta_T - \Delta_L)$$

Δ_T - выключат ~~набор~~

$$\Delta_T = V_g \left(\frac{1}{2} T_s - 2t_a \right)$$

$$\Delta_T = V_g \left(\frac{\beta}{\omega_0} - \frac{\alpha}{\omega_0} \right) \text{ - ca curve!}$$

$$\Delta_T = V_g \frac{\beta - \alpha}{\omega_0}$$

$$\Delta_L = L (-2 I_{L1})$$

$$V = \frac{2}{T_s} \left(V_g \frac{\beta - \alpha}{\omega_0} + 2L I_{L1} \right)$$

$$\frac{V}{V_g} = M = \frac{2}{T_s} \left(\frac{\beta - \alpha}{\omega_0} + \frac{1}{\omega_0} \cdot 2 \cdot \frac{\beta}{\omega_0 L} \cdot \frac{I_{L1}}{I_{L1}} \right)$$

(2x)

$$M = \frac{1}{\alpha} (\beta - \alpha + 2 I_{L1})$$

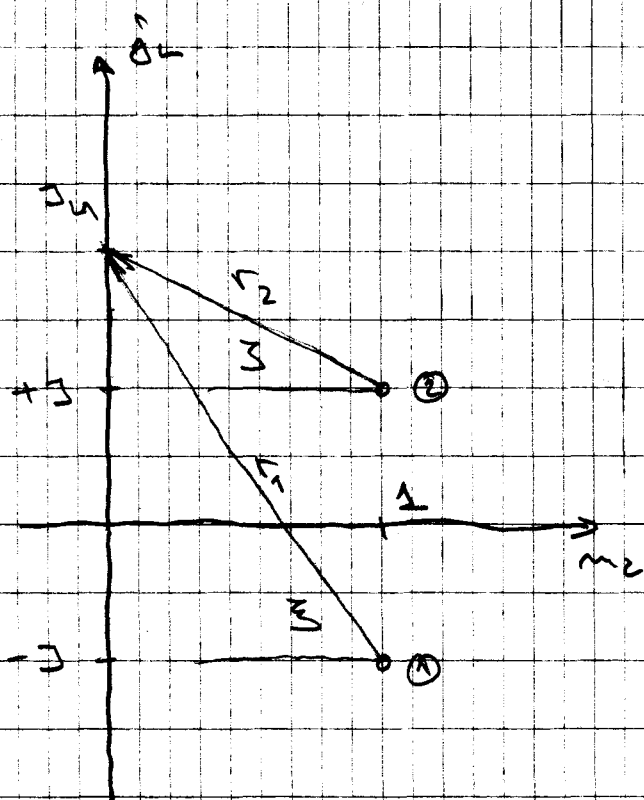
$$M = \frac{2}{\alpha} \left(\frac{\beta - \alpha}{2} + I_{L1} \right)$$

$$\frac{M_x}{2} = (\varphi + J_{L1}) \quad (0)$$

$$\varphi = \frac{J_{L1} - J_{L2}}{2}$$

- Теорема: заменим J_{L1} , J_{L2} и α на J и α

① определяем σ_1 и σ_2



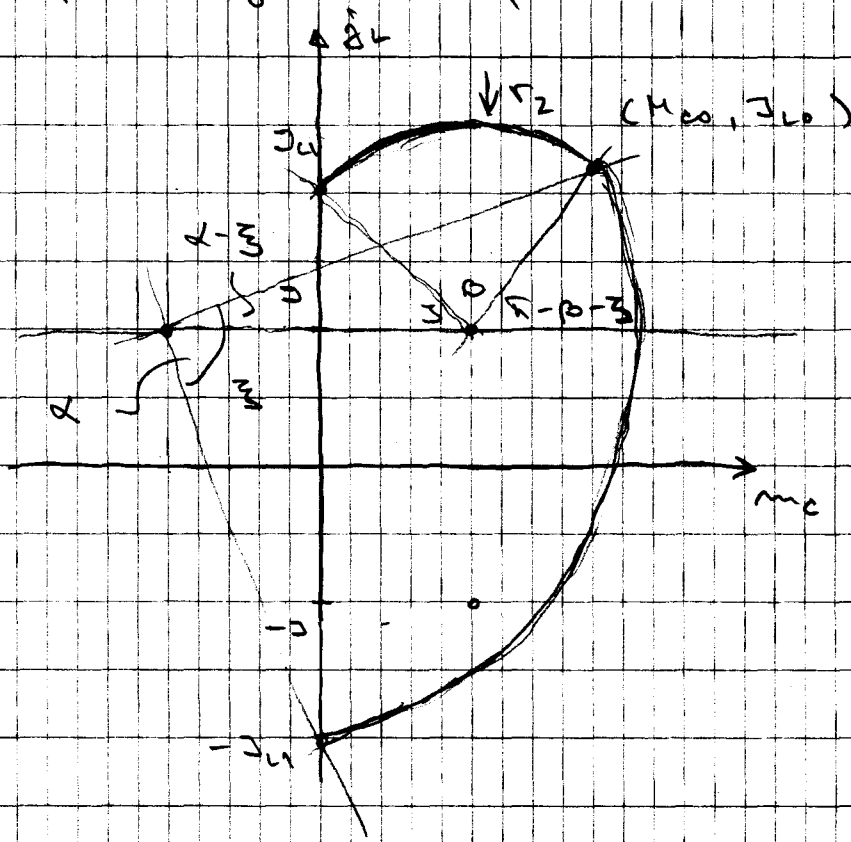
$$\sigma_2 \sin \xi = J_{L1} - J \quad (1)$$

$$\sigma_2 \cos \xi = 1 \quad (2)$$

$$\sigma_1 \sin \xi = J_{L1} + J \quad (3)$$

$$\sigma_1 \cos \xi = 1 \quad (4)$$

② *analogische Symmetrie* verdeutlicht in J_{L0}



$$J_{L0} = J + r_2 \sin(\alpha - \beta - \gamma)$$

$$J_{L0} = J + r_2 \sin(\beta + \gamma) \quad (5)$$

$$J_{L0} = J + r_1 \sin(\alpha - \gamma) \quad (6)$$

$$r_2 \sin(\beta + \gamma) = r_1 \sin(\alpha - \gamma)$$

$$r_2 (\sin \beta \cos \gamma + \cos \beta \sin \gamma) =$$

$$= r_1 (\sin \alpha \cos \beta - \cos \alpha \sin \beta) \quad (7)$$

еменно $r_2 \cos \beta$, $r_2 \sin \beta$, $r_1 \cos \beta$,
 $r_1 \sin \beta$ соответственно (1) - (4)

$$\sin \alpha - (J_1 + J) \cos \alpha = \sin \beta + (J_1 - J) \cos \beta \quad (8)$$

мы знаем, что $\frac{\alpha + \beta}{2} = \frac{\pi}{2}$, $\frac{\beta - \alpha}{2} = \varphi$

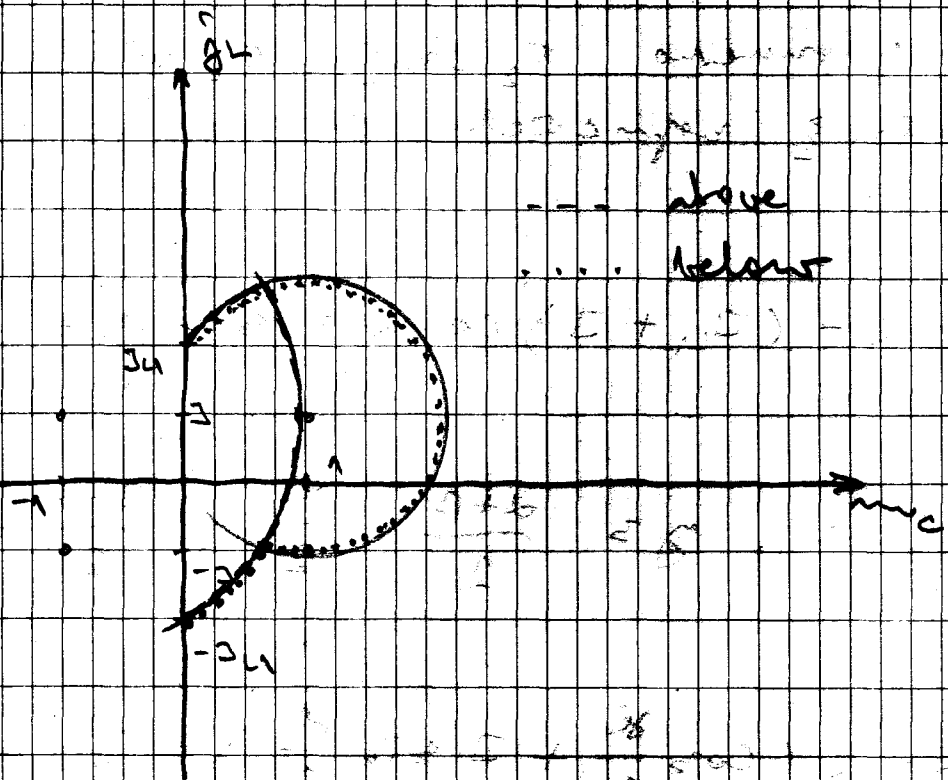
$$-\sin \varphi \left(\cos \frac{\pi}{2} + J \sin \frac{\pi}{2} \right) = J_1 \cos \frac{\pi}{2} \cos \varphi \quad (9)$$

③ найдем значение M_{co}

$$M_{co} = 1 + r_2 \cos (\pi - \beta - \beta)$$

$$M_{co} = 1 - r_2 \cos (\beta + \beta) \quad (10)$$

$$M_{co} = r_1 \cos (\alpha - \beta) - 1 \quad (11)$$



у з'являється

$$1 - \Gamma_2 \cos(\beta + \zeta) = \Gamma_1 \cos(\alpha - \zeta) - 1$$

$$\cos \varphi \left(\cos \frac{\delta}{2} + j \sin \frac{\delta}{2} \right) = j \Gamma_L \cos \frac{\delta}{2} \sin \varphi + 1$$

(12)

із (12) у (11) елімінуємо $j \Gamma_L \cos \frac{\delta}{2}$

$$\cos \varphi = \cos \frac{\delta}{2} + j \sin \frac{\delta}{2} \quad (13)$$

$$\varphi = \pm \arccos \left(\cos \frac{\delta}{2} + j \sin \frac{\delta}{2} \right) \quad (14)$$

above resonance $\varphi = \frac{\beta - \alpha}{2} < 0$

below resonance $\varphi = \frac{\beta - \alpha}{2} > 0$

за що? бажано

$$\varphi = \begin{cases} -\arccos\left(\cos\frac{\alpha}{2} + \mathcal{J}\sin\frac{\alpha}{2}\right) & 0 < \alpha < \pi \text{ (above)} \\ \arccos\left(\cos\frac{\alpha}{2} + \mathcal{J}\sin\frac{\alpha}{2}\right) & \pi < \alpha < 2\pi \text{ (below)} \end{cases} \quad (15)$$

$$\mathcal{J}_u = -\frac{\sin\varphi}{\cos\frac{\alpha}{2}} \quad (16)$$

$$\mathcal{J}_\omega = -(\mathcal{J}^2 - 1) \operatorname{tg}\frac{\alpha}{2} \quad (17)$$

$$M_{\cos} = -\frac{\mathcal{J}\sin\varphi}{\cos\frac{\alpha}{2}} \quad (18)$$

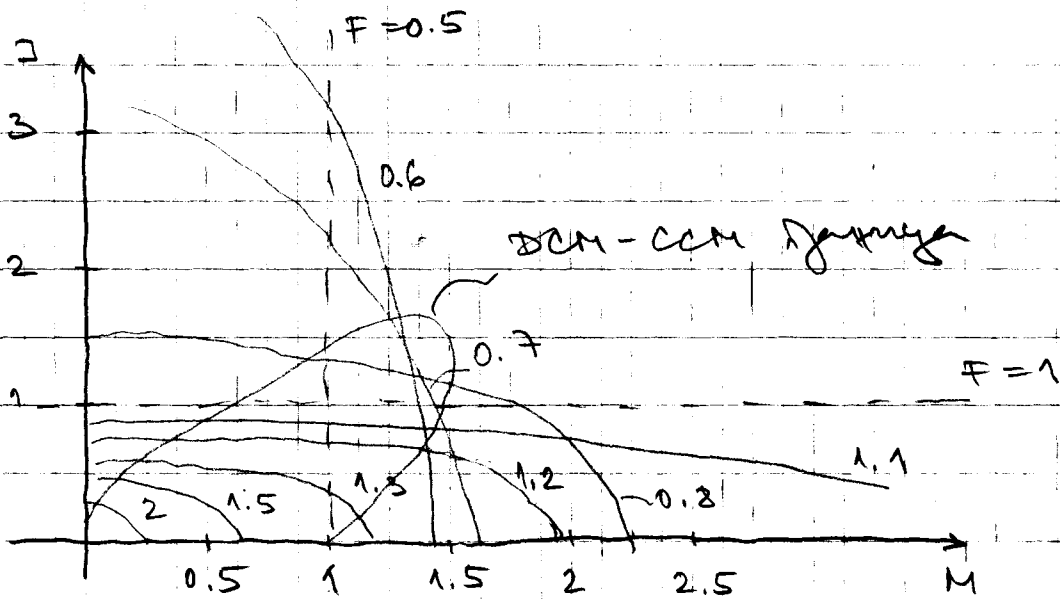
зачем (16) и (18)

$$M = \frac{2}{\alpha} \left(\varphi - \frac{\sin\varphi}{\cos\frac{\alpha}{2}} \right) \quad (17)$$

где $\varphi = M(\mathcal{J}, \alpha)$, и.ф. $M(\mathcal{J}, F)$,
 exact magnitude, does not change.

These - highly transcendental

~ изменение коэффициента трансформации F - дугам.



анализируем уравнение

$$\frac{M^2}{a^2} + \frac{J^2}{b^2} = 1$$

$$a^2 = M^2 \Big|_{J=0} = \left(1 - \left(\frac{2}{\pi} \right) \operatorname{tg} \frac{\alpha}{2} \right)^2$$

↳ open-circuit voltage

$$b^2 = J^2 \Big|_{M=0} = \left(\frac{1 - \cos \frac{\alpha}{2}}{\sin \frac{\alpha}{2}} \right)^2$$

↳ "short" -circuit current

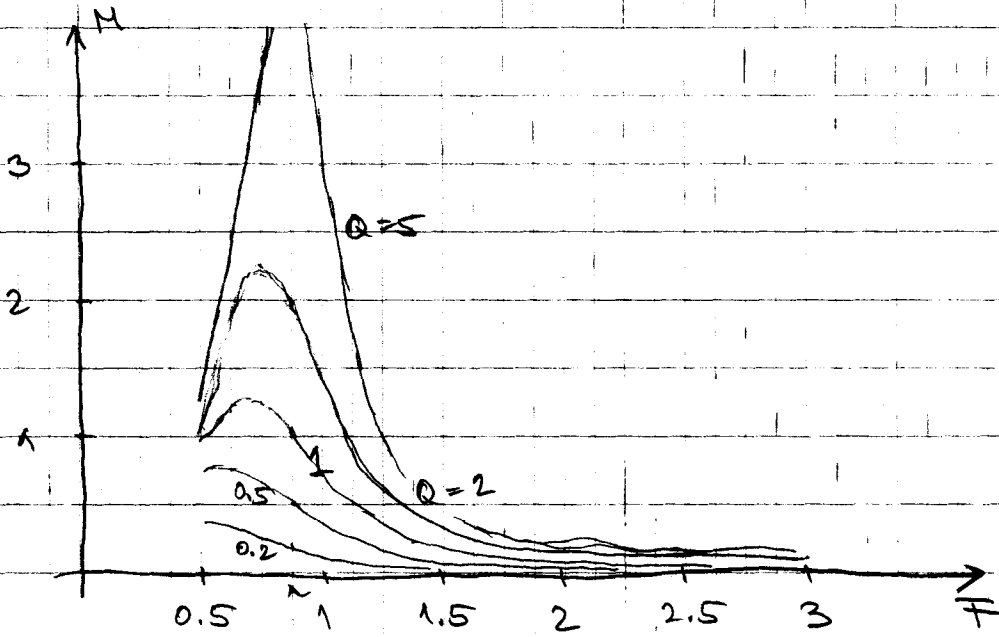
Control Plane Characteristics

$M(F)$,
Q - form

$$Q = \frac{R}{R_0} \quad (\text{parallel!})$$

$$J = \frac{1}{Q}$$

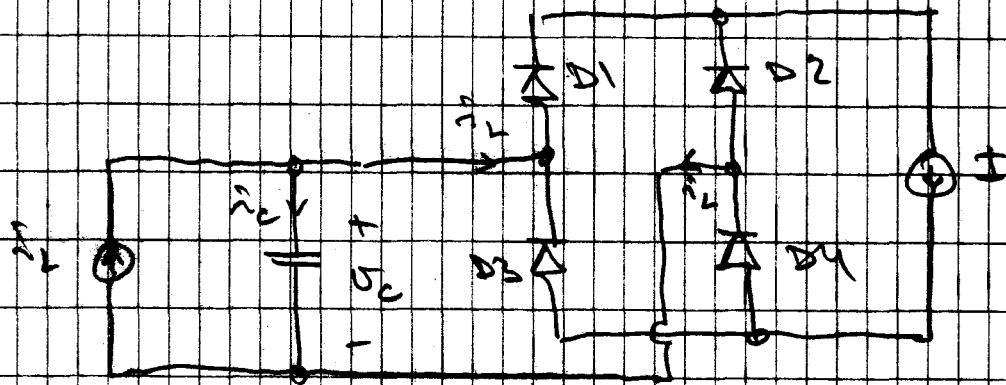
$$M = \frac{1}{\sqrt{\frac{1}{a^2} + \frac{1}{Q^2 b^2}}}$$



↑
Qm, gain for type delay

Discontinuous Conduction Mode

- qyano SDC, lag je pnat ksqcazayz
xyra - de u gnoqe z jazy boje
- qyate de u wayy u wayy peroxnce ano z
exlyqy, qyatezayz
- paznasjane:



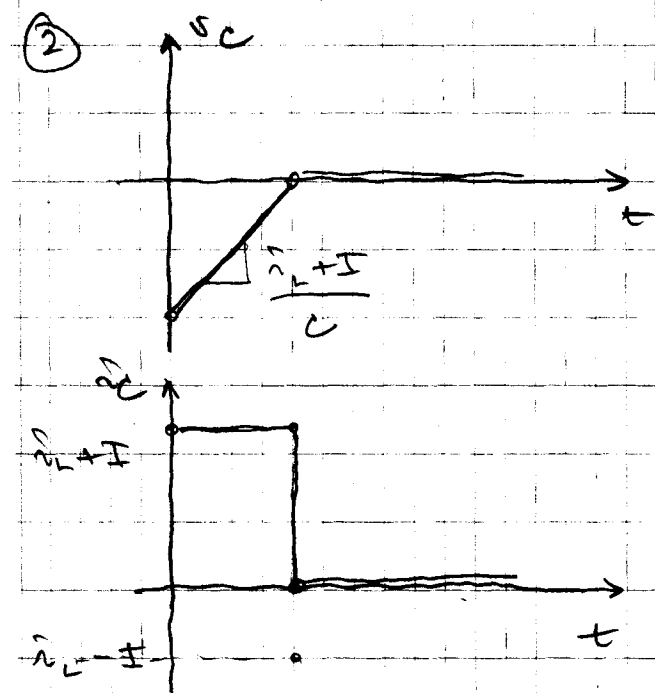
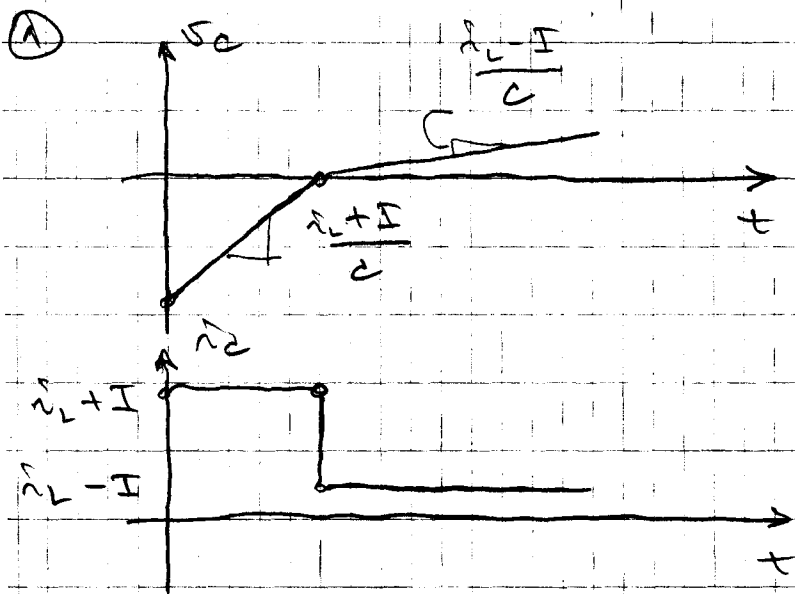
$$V_c(t) < 0 - \text{yber}$$

$I_L \cong \text{const}$ covan ksqcazayz

comparchu

$$\textcircled{1} \quad I_L > I$$

$$\textcircled{2} \quad I_L < I$$



↑ $i_L < i_c$, $v_c < 0$, i_{D1} and i_{D2} are same
 the same type!

$$i_{D1} + i_{D2} = I$$

$$i_{D1} = i_{D3} + i_L$$

$$i_{D3} + i_{D4} = I$$

$$i_{D4} = i_{D2} + i_L$$

L charging current

gegebenen charakterist.

$$\left. \begin{aligned} \vec{r}_{D1} &= \vec{r}_{D4} \\ \vec{r}_{D3} &= \vec{r}_{D2} \end{aligned} \right\} \text{jeil. vorkommenden je zwei von}$$

$$\vec{r}_{D1} + \vec{r}_{D2} = \mathbb{I}$$

$$\vec{r}_{D1} - \vec{r}_{D3} = \vec{r}_L$$

$$\vec{r}_{D1} - \vec{r}_{D2} = \vec{r}_L$$

$$2 \vec{r}_{D1} = \mathbb{I} + \vec{r}_L$$

$$\vec{r}_{D1} = \vec{r}_{D4} = \frac{1}{2} (\mathbb{I} + \vec{r}_L)$$

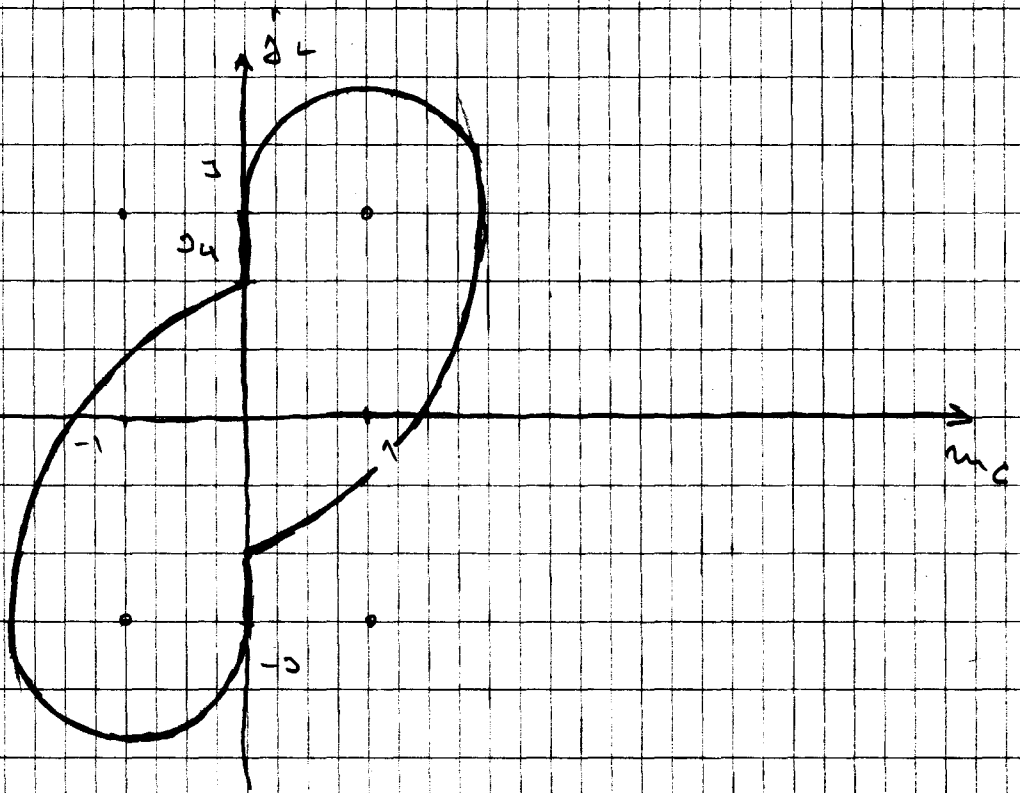
$$2 \vec{r}_{D2} = \mathbb{I} - \vec{r}_L$$

$$\vec{r}_{D2} = \vec{r}_{D3} = \frac{1}{2} (\mathbb{I} - \vec{r}_L)$$

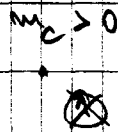
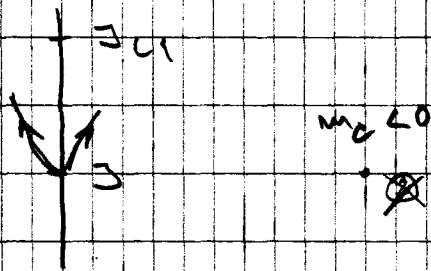
$$\vec{r}_L < \mathbb{I} \quad \text{da} \quad \vec{r}_D > 0!$$

Wares da gar \vec{r}_L ne größer als \mathbb{I} !

- fazza falan



de mome



←
Q2 Q3 off,
de mome yekayp
* - 1

regun mome $m_c = 0$ $j\omega_1 > |j\omega_2| < j$

CCM - DCM boundary

$$D_m < D$$

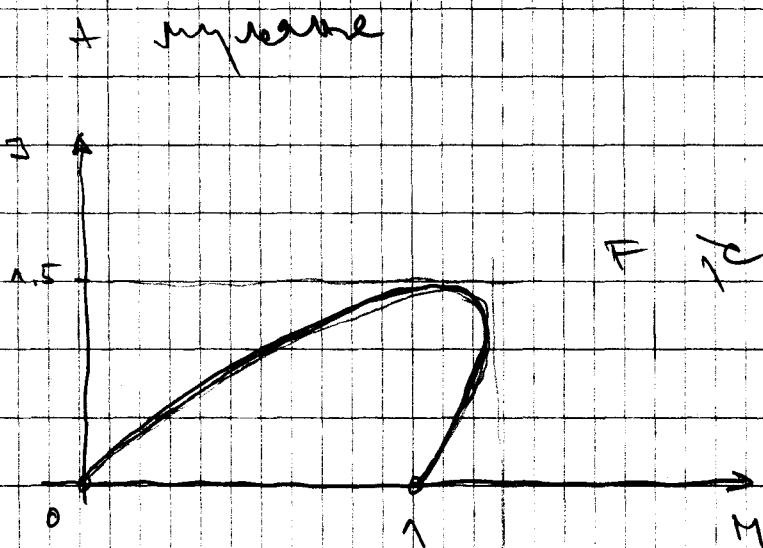
$$D > D_{crit} \rightarrow DCM$$

$$D < D_{crit} \rightarrow CCM$$

$$D_{crit} = -\frac{1}{2} \sin^2 \phi + \sqrt{\frac{\sin^2 \phi}{2} + \frac{1}{4} \sin^2 \phi}$$

$$D_m = -\frac{\sin \phi}{\cos \frac{\phi}{2}}$$

$$C = - \dots$$



Результат 3а DCM

