#### Sinteza električnih filtara

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# Overview

- Analog filter specification
- Analog filter design steps
- Analog filter classification
- Sensitivity
- Optimum cascading sequence
- Examples
- MATLAB cheb1ord, cheb1ap

# What are analog filters?

- **Analog filters** are frequency-selective circuits that are used to amplify or attenuate a single sinusoidal signal component or a portion of the signal frequency spectrum
- **Passband** is a range of frequencies in which the sinusoidal signals are amplified or passed without considerable attenuation
- **Stopband** is a frequency range in which the sinusoidal signals are significantly attenuated
- **Specification** is the required minimum and maximum of attenuation or amplification, along with corresponding edge frequencies of passbands and stopbands

# What is analog filter design?

- Analog filter design is a process in which we construct an electrical circuit that meets the given specification
- Design starts with the specification and it consists of four basic steps:
  - 1. approximation
  - 2. realization
  - 3. study of imperfections
  - 4. implementation
- There is an infinite number of circuits that meet the specification; therefore, the filter design is by no means unique

# **Classic filter design**



# **Specification example**

- Assume we want to design an analog lowpass filter that passes signals over the range  $0 \le f \le F_p$  and attenuates signals for  $f \ge F_s > F_p$
- Range  $0 \le f \le F_p$  is passband, and  $f \ge F_s$  is stopband;  $F_p$  is **passband edge frequency** and  $F_s$  is **stopband edge frequency**
- We require that attenuation in passband must not exceed A<sub>p</sub> dB in stopband should be no less than A<sub>s</sub> dB
- $A_p$  is maximum *passband attenuation*  $A_s$  is minimum *stopband attenuation*
- Four quantities that specify lowpass filter  $S = \{F_p, F_s, A_p, A_s\}$  is the *lowpass specification*

# **Approximation step**

- **Approximation step**: we construct filter transfer function H(s), which is a rational function in the complex frequency *s*
- Attenuation approximation function, simply attenuation,  $A(f) = -20 \log_{10}|H(j2\pi f)|$ , must satisfy the specification *S*

$$0 \le A(f) \le A_p, \qquad 0 \le f \le F_p$$
$$A_s \le A(f), \qquad F_s \le f$$

# **Realization step**

- **Realization step** is the process of converting the transfer function into a circuit (sometimes called the realization)
- Designers are interested in realizations which are economical, simple, cheap, with small noise and distortion, and with high dynamic range and which are not seriously affected by small changes in the element values (tolerances, temperature and humidity variations, aging drift)
- Numerical values of the elements are calculated from the transfer function

# Study of imperfections

- In practice, the filter is implemented with nonideal elements
- Designer must accomplish the study of imperfections which includes tolerance analysis and study of parasitics
- If specification can be met only with high-precision expensive components, then the designer has to choose another transfer function and reevaluate realization or approximation steps

# Implementation step

- In the *implementation step* a device called the product prototype, also called the *implementation*, is constructed and tested
- Cost of the mass production depends on the type of components, packaging, methods of manufacturing, testing, and tuning
- The best implementation is a device with no need for tuning
- If the requirements are not met, then the realization step (new circuit) or the approximation step must be redone

# Analog filter classification (1)

- Lowpass filter passes signals over the range  $0 \le f \le F_p$  but attenuates signals for  $f \ge F_s > F_p$
- *Highpass filter* passes signals for  $f \ge F_p$  but attenuates signals over the range  $0 \le f \le F_s < F_p$
- **Bandpass filter** passes signals for  $F_{p1} \le f \le F_{p2}$ but attenuates signals for  $0 \le f \le F_{s1} < F_{p1}$  and  $f \ge F_{s2} > F_{p2}$
- **Bandreject** or **bandstop filter** passes signals for  $0 \le f \le F_{p1} < F_{s1}$  and  $f \ge F_{p2} > F_{s2}$ but attenuates signals over the range  $F_{s1} \le f \le F_{s2}$

# Analog filter classification (2)

- Allpass filter or phase equalizer passes signals without attenuation and shapes the phase response
- Lowpass-notch filter rejects signals at frequencies  $f \approx f_z$  but passes signals at high frequencies  $(f >> f_z)$  with some attenuation
- **Highpass-notch filter** rejects sinusoidal signals at frequencies  $f \approx f_z$  but passes signals at low frequencies ( $f << f_z$ ) with some attenuation
- **Amplitude equalizer** or **bump filter** slightly amplifies or attenuates signals over a range of frequencies

#### Decomposition of transfer functions

- To reduce the sensitivity of a transfer function with respect to deviations of the element values and to simplify the tuning process of the filter, it is preferable to realize the filter by a **cascade** of the **first-order** and **second-order** filter sections
- Cascade approach consists of realizing each of the sections by an appropriate circuit and connecting these circuits in cascade
- Overall transfer function is expressed as a product of first-order and second-order functions

## Optimum cascading sequence

- After a transfer function is decomposed into first-order and second-order functions designer has to choose the *optimal cascading sequence*
- For the maximal dynamic range, the optimal sequence of the second-order filter sections is the sequence in which the preceding section has lower Q-factor than the following section
- If the input signal contains an undesired signal with very large amplitude, this signal has to be filtered out by the very first section, which should have a transfer function zero at the frequency of the undesired signal

# Production yield

- Before the filter is manufactured, the effects of manufacturing tolerances and component imperfections have to be analyzed
- Designer should predict variations of the filter performances and the production yield
- Yield is the ratio of (a) the number of manufactured filters satisfying the specification to (b) the total number of manufactured filters
- High yield is desirable for **profitability**

# Sensitivity

- The simplest way to predict the yield is to use the concept of sensitivity assuming that the component changes are small
- Single-parameter relative sensitivity of a function

$$S_{x_i}^F = \frac{x_i}{F} \frac{\partial F}{\partial x_i}$$

• **Expected relative variation** in function

$$\frac{\Delta F}{F} = \sum_{i=1}^{n} S_{x_i}^F \frac{\Delta x_i}{x_i}$$

• Example: If a sensitivity is 1, then a 1% change in the variable (component value) will cause a 1% change in the function; when a sensitivity is zero, then any change in variable will not affect the function

#### Upper limit of the relative variation

• Worst-case method gives the absolute relative variation assuming that all changes are at their extreme

$$\frac{\Delta F}{F}\Big|_{\text{worst case}} = \sum_{i=1}^{n} \left| S_{x_i}^F \frac{\Delta x_i}{x_i} \right|$$

• Schoeffler criterion method is closer to the variation obtained by statistical computations

$$\frac{\Delta F}{F}\Big|_{\text{Schoeffler}} = \sqrt{\sum_{i=1}^{n} \left|S_{x_i}^F \frac{\Delta x_i}{x_i}\right|^2}$$

 Monte Carlo method relies on extensive simulation of the filter realization (circuit) with randomly chosen element values

## Osetljivost amplitudske funkcije

$$H(s) = \frac{1}{s^2 + \frac{\omega_p}{Q_p}s + \omega_p^2}$$

The squared magnitude response is  

$$M^{2}(\omega) = \frac{1}{\left(-\omega^{2} + \omega_{p}^{2}\right)^{2} + \left(\frac{\omega_{p}}{Q_{p}}\right)^{2} \omega^{2}}$$

# Amplitudska funkcija - pol

The sensitivity of the magnitude response to the pole magnitude is

$$S_{\omega_p}^{M(\omega)}(\omega) = -\frac{2\left(1 - \frac{\omega^2}{\omega_p^2}\right) + \frac{\omega^2}{\omega_p^2 Q_p^2}}{\left(1 - \frac{\omega^2}{\omega_p^2}\right)^2 + \frac{\omega^2}{\omega_p^2 Q_p^2}}$$

The extremes of 
$$S_{\omega_p}^{M(\omega)}(\omega)$$
 are  
 $S_{\omega_p}^{M(\omega)}(\omega)\Big|_{\min} \approx -Q_p$  for  $\frac{\omega}{\omega_p} \approx 1 - \frac{1}{2Q_p}$  and  $Q_p \gg 1$   
 $S_{\omega_p}^{M(\omega)}(\omega)\Big|_{\max} \approx Q_p$  for  $\frac{\omega}{\omega_p} \approx 1 + \frac{1}{2Q_p}$  and  $Q_p \gg 1$ 

#### Amplitudska funkcija - pol



## Amplitudska funkcija – Q-factor



$$S_{Q_p}^{M(\omega)}(\omega)\Big|_{\max} = 1$$

$$\left|S_{\omega_p}^{M(\omega)}(\omega)\Big|_{\max} \approx Q_p \left|S_{Q_p}^{M(\omega)}(\omega)\right|_{\max}\right|_{\max}$$

## Amplitudska funkcija – Q-factor



# Najgori slučaj



## Osetljivost slabljenja

$$\Delta G(\omega) \approx S_{x_i}^{G(\omega)} \frac{\Delta x_i}{x_i} = \frac{20}{\ln 10} S_{x_i}^{M(\omega)} \frac{\Delta x_i}{x_i} \approx 8.686 \ S_{x_i}^{M(\omega)} \frac{\Delta x_i}{x_i}$$

#### Osetljivost na nule prenosa



## Sumarna osetljivost

$$S_x^F = \sum_{i=1}^n S_{x_i}^F$$

$$\sum_{i=1}^{n_R} S_{R_i}^{Q_p} = \sum_{k=1}^{n_C} S_{C_k}^{Q_p} = 0$$
$$\sum_{i=1}^{n_R} S_{R_i}^{\omega_p} = \sum_{k=1}^{n_C} S_{C_k}^{\omega_p} = -1$$

# Osetljivost je 0!

$$\frac{\Delta M(\omega)}{M(\omega)} = S_{\omega_p}^{M(\omega)} \frac{\Delta x}{x} \left( \sum_{i=1}^{n_R} S_{R_i}^{\omega_p} - \sum_{k=1}^{n_C} S_{C_k}^{\omega_p} \right)$$

$$\frac{\Delta R}{R} = -\frac{\Delta C}{C} = \frac{\Delta x}{x}$$
Temperaturni  
koeficijent je isti  
a suprotnog znaka
$$\frac{\Delta M(\omega)}{M(\omega)} = 0$$

#### Tolerancije elemenata

$$x = x_0(1 + \gamma_x)$$



#### Temperaturne promene

$$x = x_0(1 + \alpha_x \Delta T)$$
  
$$T = T_0 + \Delta T$$
  
Sobna temperatura  
$$\alpha_x = 100 \cdot 10^{-6} \text{ 1/K}.$$

temperature coefficient of 100 ppm/K

### Efekti starenja

$$x = x_0(1 + \beta_x \sqrt{t})$$

 $\beta_x$  is in ppm/yr

#### Vrednost i relativna promena

$$x = x_0(1 + \gamma_x + \alpha_x \Delta T + \beta_x \sqrt{t})$$



## Proizvod osetljivost-pojačanje



#### Example specification and design

Fp = 3400; Fs = 5000;Ap = 1; As = 20;[n, Wn] = cheb1ord(Fp, Fs, Ap, As, 's')[z,p,k] = cheb1ap(n, Ap);Q = (-abs(p)./(2\*real(p))); $w = round(abs(p)^{*}(2^{*}pi^{*}Fp));$  $D1 = [1 w(1)/Q(1) w(1)^{2}];$  $D2 = [1 w(2)/Q(2) w(2)^{2}];$  $N1 = w(1)^{2}; N2 = w(2)^{2};$ D = conv(D1,D2); $N = 10^{(-Ap/20)*conv(N1,N2)};$ Fplot = 6000;f = 0:Fplot/200:Fplot;H = freqs(N,D,2\*pi\*f);M = -20\*log10(abs(H));subplot(2,1,1)plot(f,M,[0 Fp Fp],[Ap Ap As],'r--',... [Fs Fs Fplot],[0 As As],'r--') xlabel('f (Hz)'); ylabel('A (dB)') subplot(2,1,2)drawschematic(0,0,4,5,8,'b')



## Example sensitivity analysis

Pole magnitudes and Q-factors decreased by 10%: passband specification violated

Pole magnitudes and Q-factors increased by 10%: stopband specification violated

See the Matlab script Lecture06sens.m



# Anadigm chip

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#### **?**× Set CAM Parameters ANx21 Standard (SumInv 1.1.0): Inverting Sum Stage Anadigm Approved CAM Instance name and clock frequency Symbol Notes SumInv1 Instance Name: It is not recommended to run this CAM's clock (CLOCKA) 0 OK. CLOCKA (kHz) at a frequency greater than 4 MHz. Cancel Help CAM Options O Off 💿 On Input 3 Documentation Adder and gain C Code... implementation CAM Parameters Value: Limits: Realized Parameter: Gain 1 (UpperInput) 0.1 0.0100 To 100 0.100 0.5 Gain 2 (MiddleInput) 0.0100 To 25.5 0.500 Gain 3 (LowerInput) 1 0.0100 To 25.5 1.00













