

# Sinteza električnih filtara

**Dr Miroslav Lutovac**

## Cilj predmeta

Savladati teorijske osnove  
analognih električnih filtara

Korišćenje računarskih alata  
za projektovanje filtara

# Ishod predmeta

- Da se na osnovu zahteva za rad uređaja
  - definišu specifikacije koje filter treba da zadovolji
  - da se izabere najbolja aproksimacija
  - da se izabere tehnologiju za implementaciju.
- Koristeći alate da se
  - projektuje filter (sinteza)
  - uradi simulacija
  - uradi optimizacija

# Teorijska nastava

- Uloga filtara u složenim sistemima i uređajima
- Izbor aproksimacione funkcije
- Projektovanje korišćenjem računarskih alata
- Realizacija filtara
  - aktivni sa operacionim pojačavačima
  - OTA
  - SS
  - pasivni filtri
  - univerzalna filtarska integrisana kola
  - programabilna analogna kola

# Praktična nastava

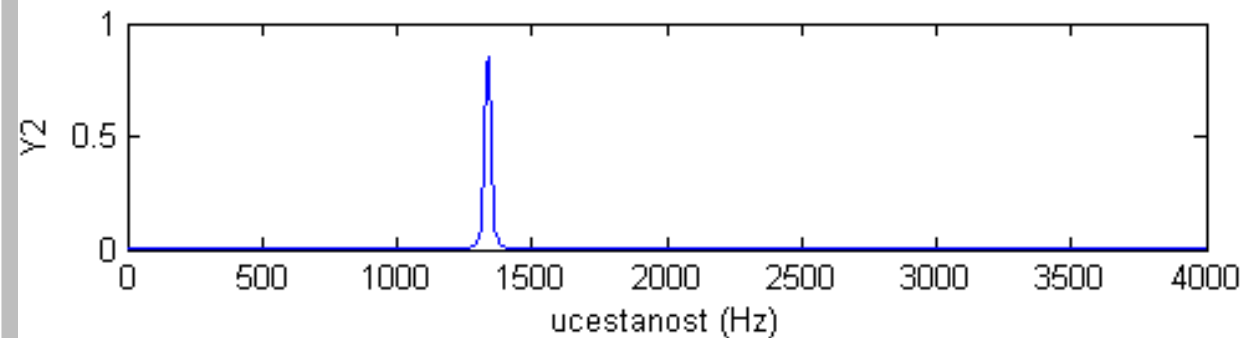
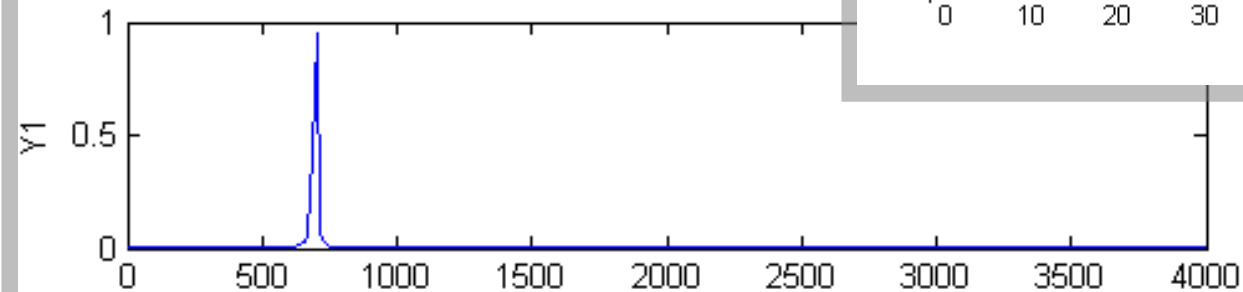
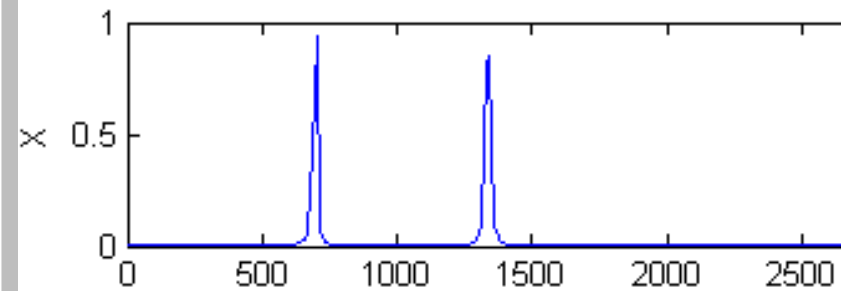
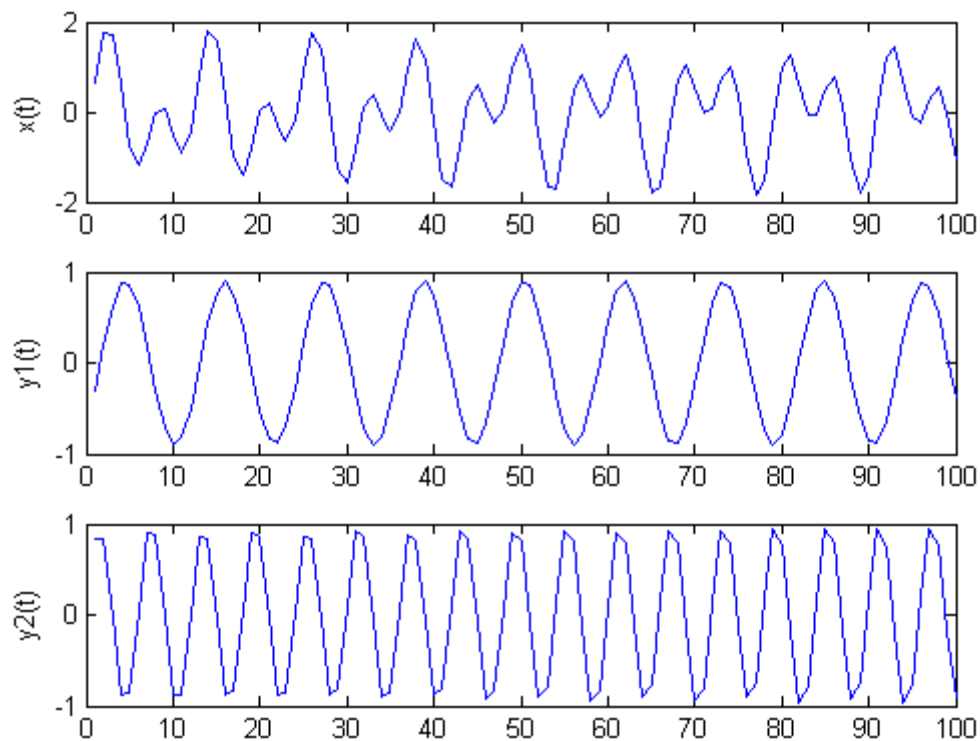
- Korišćenje standardnih računarskih alata za
  - projektovanje
  - analizu i
  - simulaciju
- rada električnih filtara

# Literatura

1. M. Lutovac, D. Tosic, B. Evans,  
**Filter Design for Signal Processing  
Using MATLAB and Mathematica,**  
Prentice Hall, New Jersey, 2001
2. G. Moschytz, P. Horn,  
**Active filter design handbook,**  
John Wiley, New York, 1981
3. G. Daryanani,  
**Principles of Active Network Synthesis  
and Design,**  
John Wiley, New York, 1976
4. **Anadigm,** Software user manual

# Telefon #2

697Hz + 1336 Hz

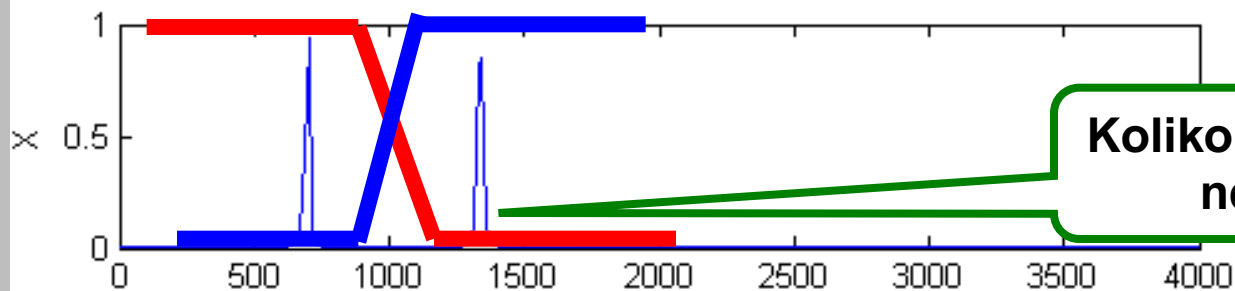


# Telefon #2

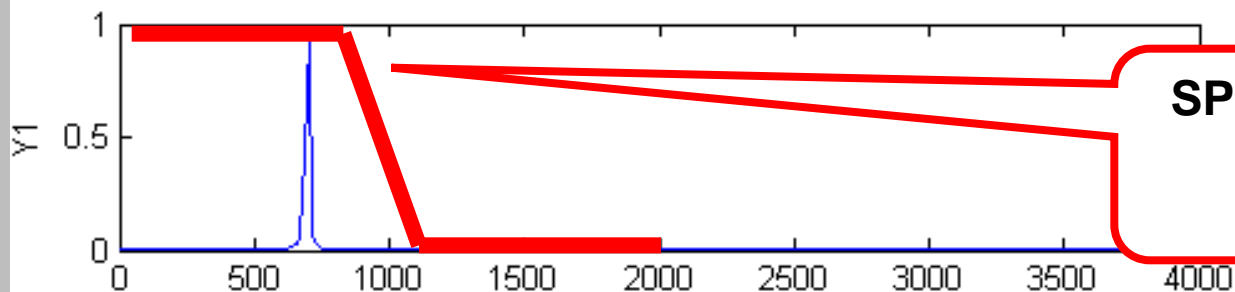
697Hz + 1336 Hz

697, 770, 852, 941 Hz

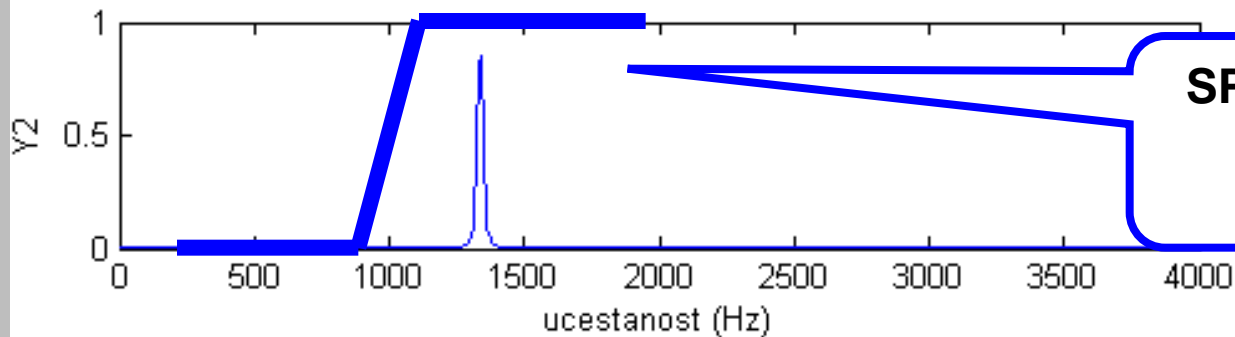
1209, 1336, 1477, 1633 Hz



Koliko da oslabimo signal na nekoj učestanosti?

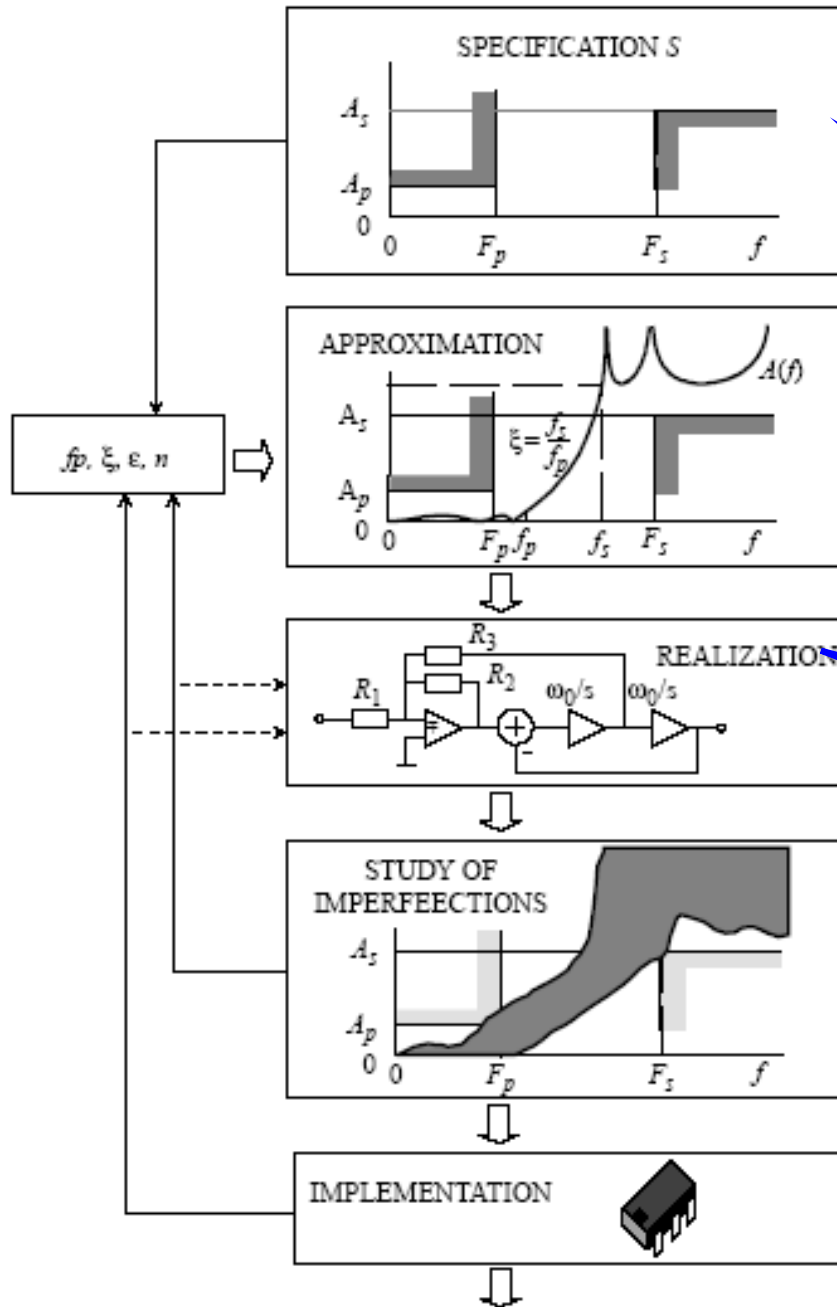


SPECIFIKACIJE ZA FILTAR  
PROPUSNIK NISKIH  
UČESTANOSTI



SPECIFIKACIJE ZA FILTAR  
PROPUSNIK VISOKIH  
UČESTANOSTI

# Od specifikacija do realizacije



**Specifikacije**

**Sinteza**



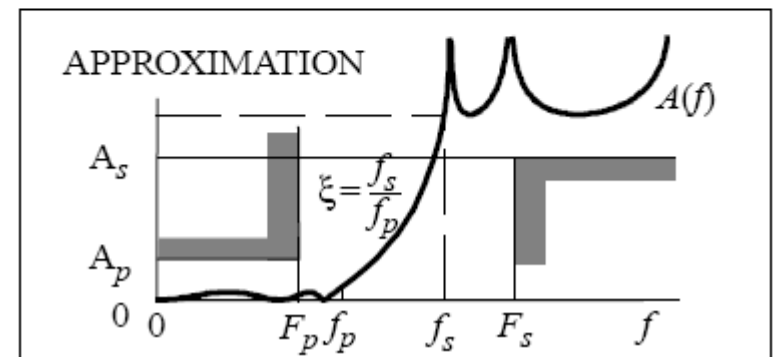
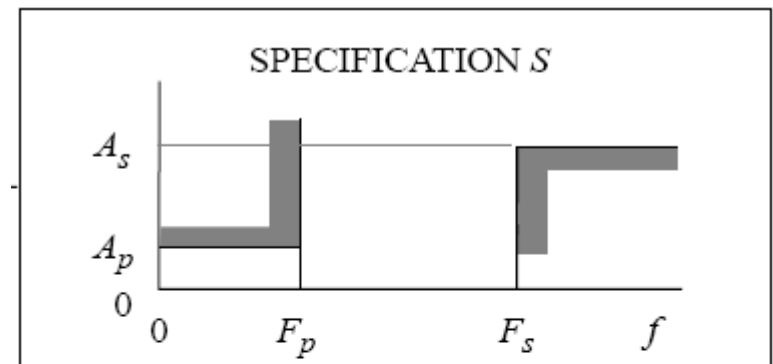
# Specifikacije

- Definišu se dozvoljene **tolerancije** u određenim frekvencijskim opsezima

$H(s)$  je racionalna funkcija kompleksne frekvencije  
 $s = \delta + j\omega$ ,  $s = j2\pi f$

$$H(s) = \frac{\sum_{k=0}^M c_k s^k}{\sum_{k=0}^N d_k s^k} = \frac{C(s)}{D(s)}$$

$$a(f) = -20 \log(|H(j2\pi f)|)$$

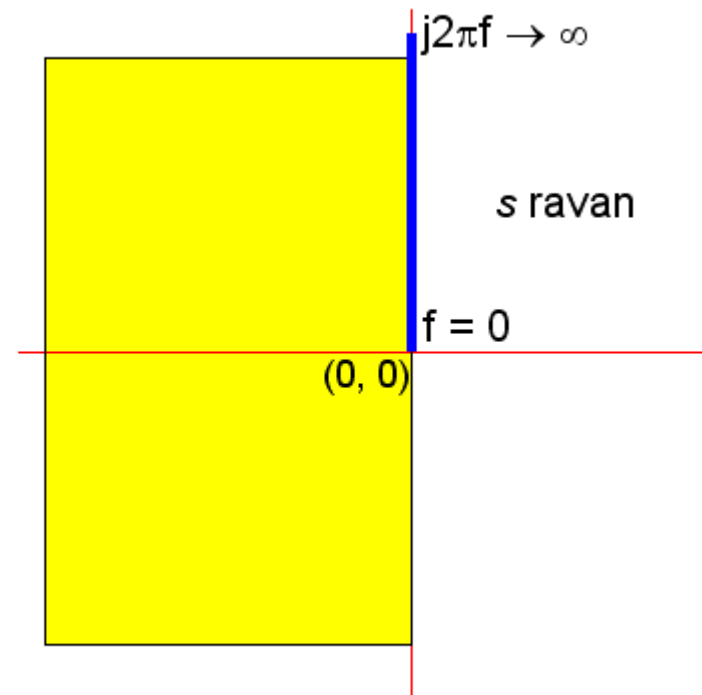


# Frekvencijski odziv

$$H(s) = \frac{\sum_{k=0}^M c_k s^k}{\sum_{k=0}^N d_k s^k} = \frac{C(s)}{D(s)}$$

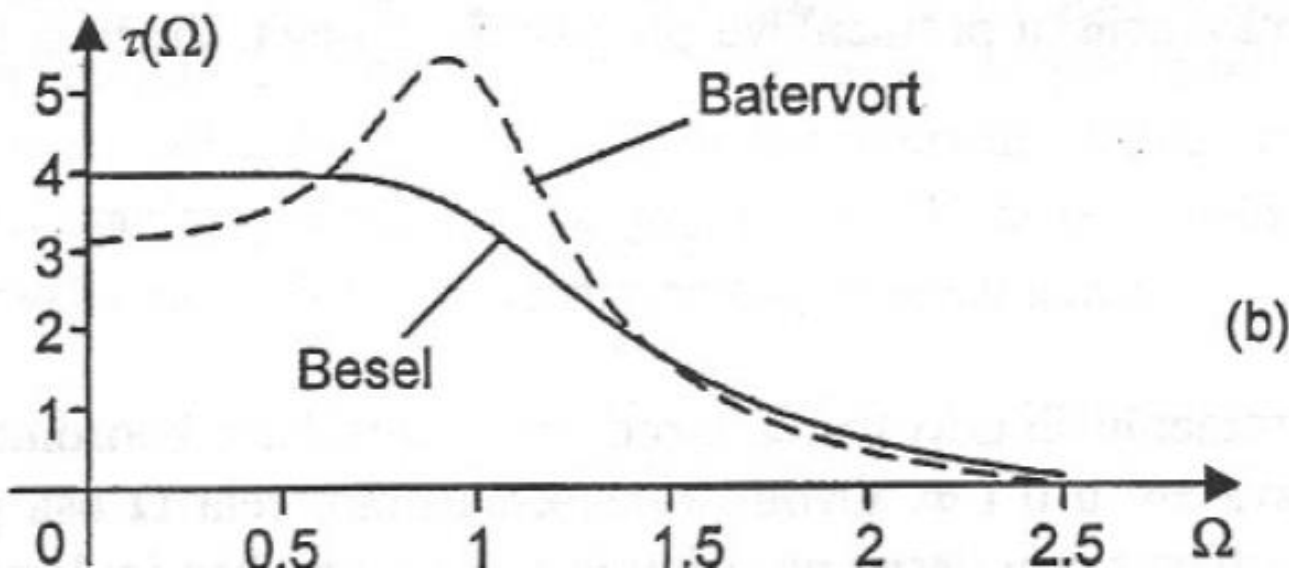
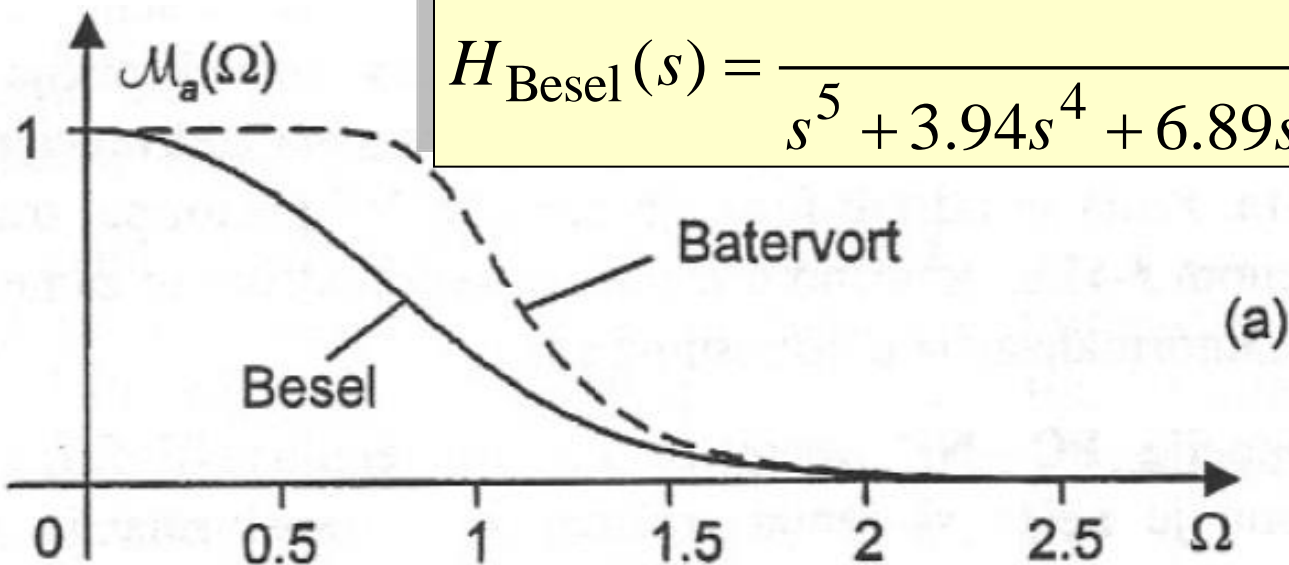
$$H(j2\pi f)$$

$$0 \leq f \leq \infty$$

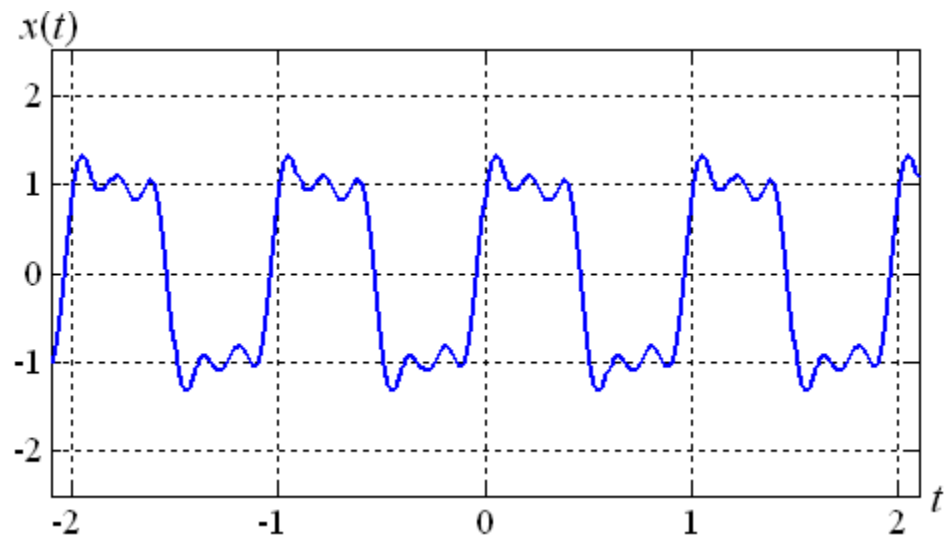
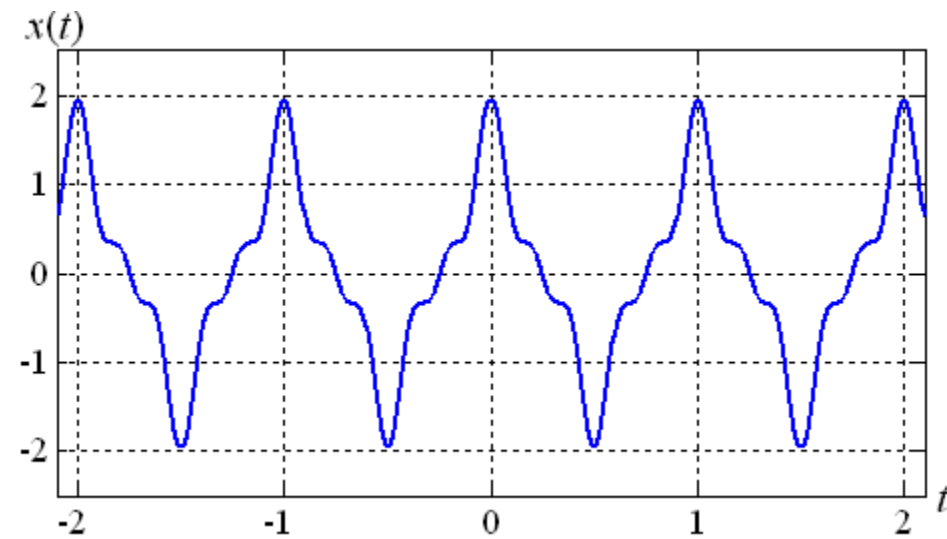
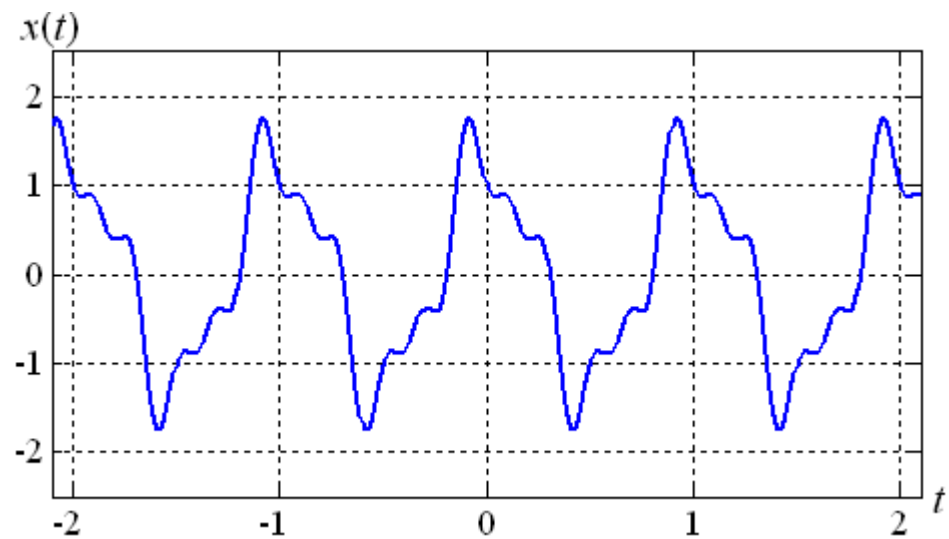
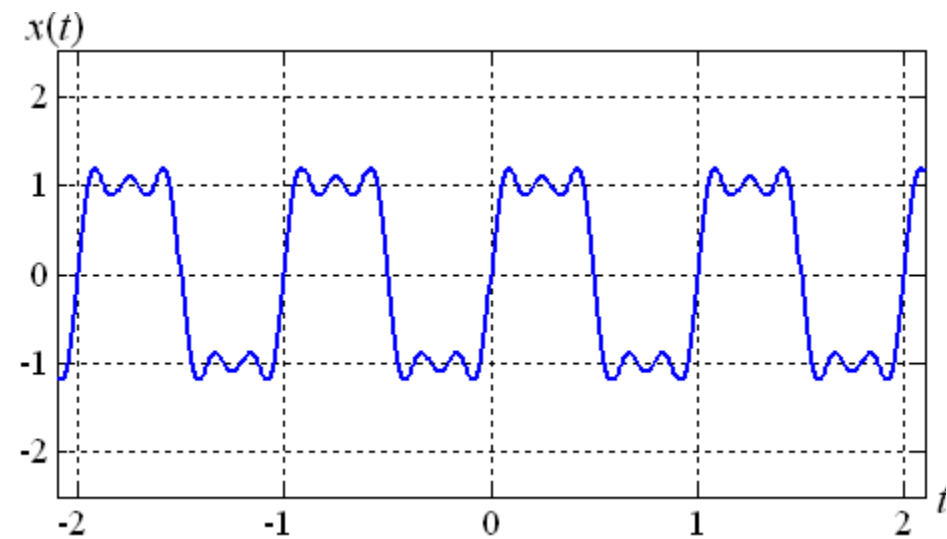


$$H_{\text{Batervort}}(s) = \frac{1}{s^5 + 3.24s^4 + 5.24s^3 + 5.24s^2 + 3.24s + 1}$$

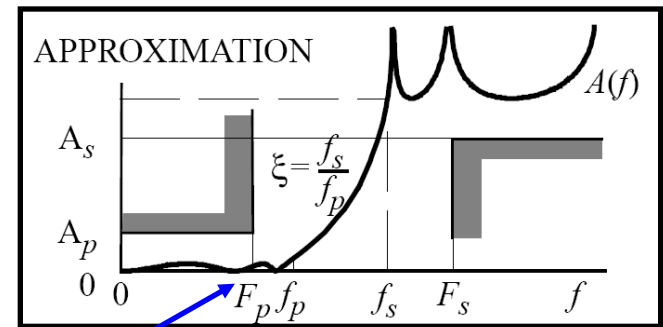
$$H_{\text{Besel}}(s) = \frac{1}{s^5 + 3.94s^4 + 6.89s^3 + 6.78s^2 + 3.81s + 1}$$



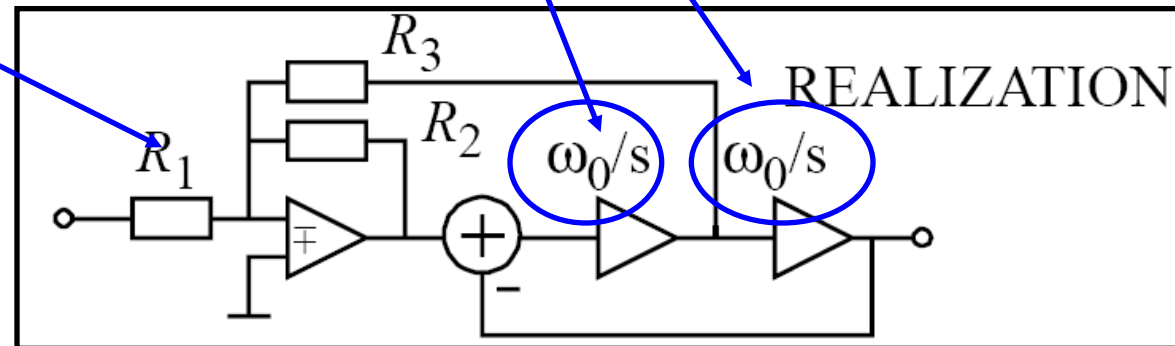
# Uticaj fazne karakteristike



# Sinteza



- Naći funkciju prenosa takvu da je racionalna funkcija po  $s$  što nižeg reda i da amplitudska karakteristika zadovoljava specifikacije
- da se koristi minimalan broj elemenata u realizaciji



# Analogni filter

- **Analogni filter** je električno kolo koje se koristi da pojača ili oslabi sinusoidalne signale ili signale koji zauzimaju određeni frekvencijski opseg
- Opseg učestanosti u kome se signali pojačavaju ili propuštaju bez većih slabljenja naziva se **propusni opseg**
- Opseg učestanosti u kome se signali značajnije slabe, naziva se **nepropusni opseg**
- **Specifikacije** su zahtevi u pogledu minimalnog dozvoljenog ili maksimalnog slabljenja ili pojačanja signala, u nekom opsegu učestanosti, a granice opsega su granične učestanosti
- **Projektovanje (sinteza)** analognog filtra je proces u kome konstruišemo kolo, odnosno izračunavamo vrednosti elemenata tako da to kolo zadovolji specifikacije

# Projektovanje - sinteza

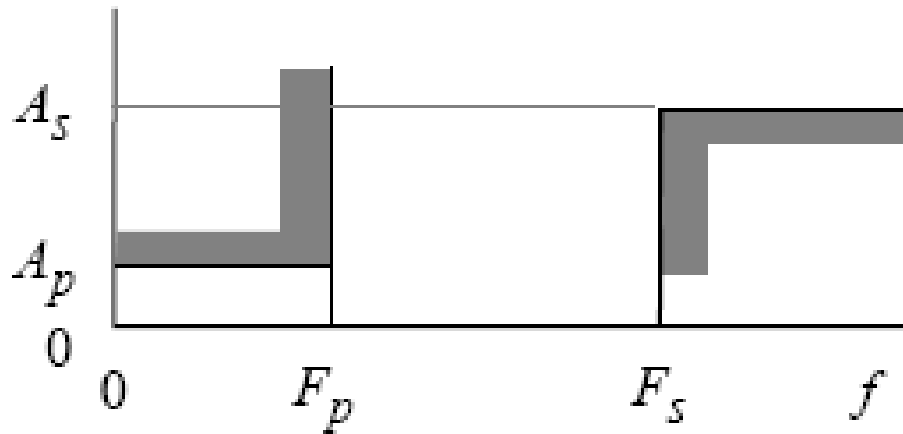
- Projektovanje se sastoji od
  - Aproksimacije
  - Realizacije
  - Analiza nesavršenosti
  - Implementacije
- Broj električnih kola koji može da se napravi a da zadovolji specifikacije je beskonačan
- Kako izabrati optimalno rešenje?

# Filtar propusnik niskih učestanosti

- Propušta sinusoidalne signale čija je učestanost u opsegu  $0 \leq f \leq f_p$
- Slabi signale čija je učestanost  $f \geq F_s > F_p$   
*to je analogni lowpass filter*
- Opseg učestanosti  $0 \leq f \leq f_p$  je propusni opseg
- Opseg učestanosti  $f \geq F_s > F_p$  je nepropusni opseg
- $F_p$  je granica propusnog opsega (*passband edge frequency*)
- $F_s$  je granica nepropusnog opsega (*stopband edge frequency*)
- Slabljenje u propusnom opsegu ne sme biti veće izvan opsega  $0 - A_p$  u dB
- Slabljenje u nepropusnom opsegu ne sme biti manje od  $A_s$  u dB,  $A_s > 0$
- $A_p$  je *maximum passband attenuation*
- $A_s$  is the *minimum stopband attenuation*
- Lista  $S = \{F_p, F_s, A_p, A_s\}$  je **specifikacija** lowpass filtra



# Tolerancije karakteristike slabljenja



$$A(f) = -20 \log(\bullet^*(f))$$

$$S = \{F_p, F_s, A_p, A_s\}$$

$$0 \leq A(f) \leq A_p \text{ za } 0 \leq f \leq F_p$$

$$A_s \leq A(f) \leq +\infty \text{ za } F_s \leq f < +\infty$$

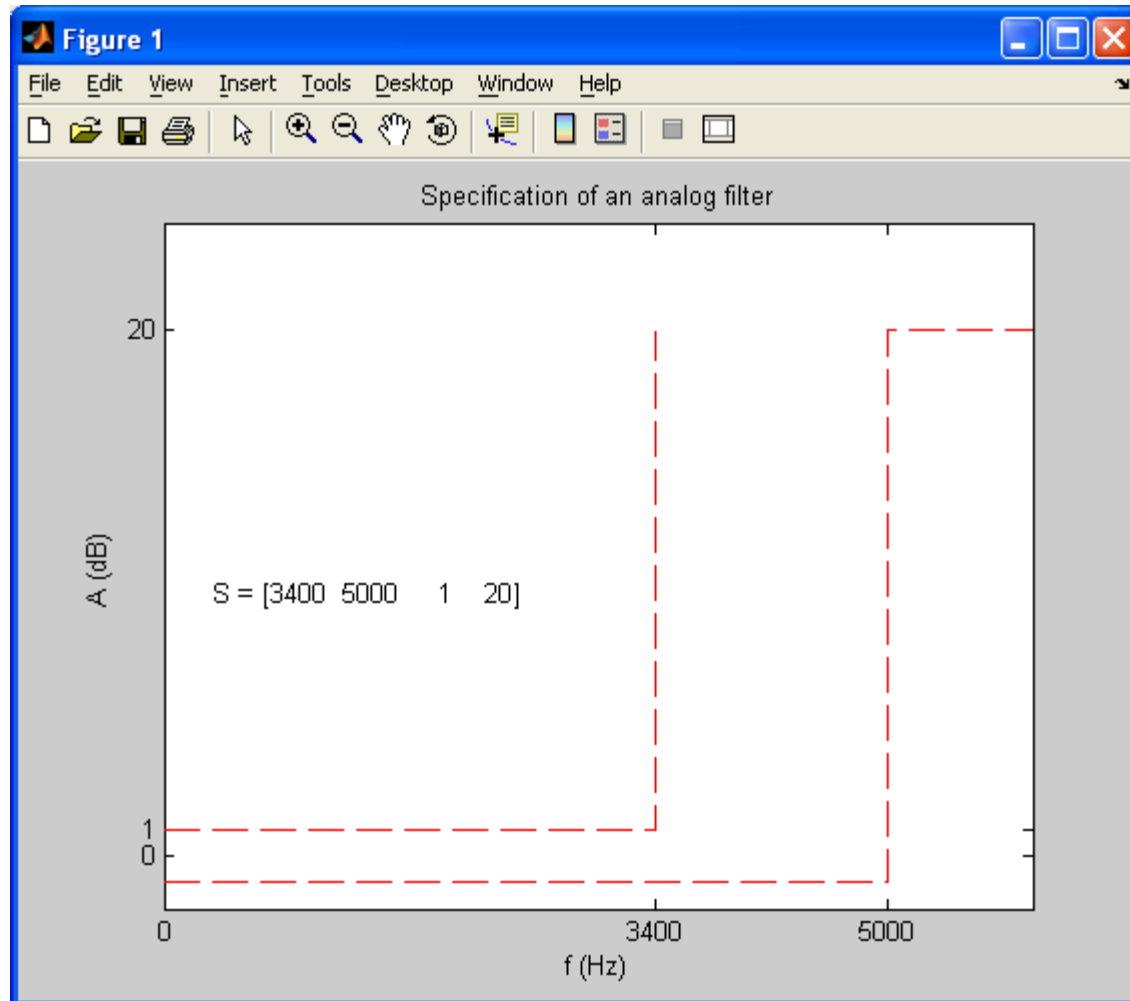
Propusni opseg

Nepropusni opseg

# Primer projektovanja

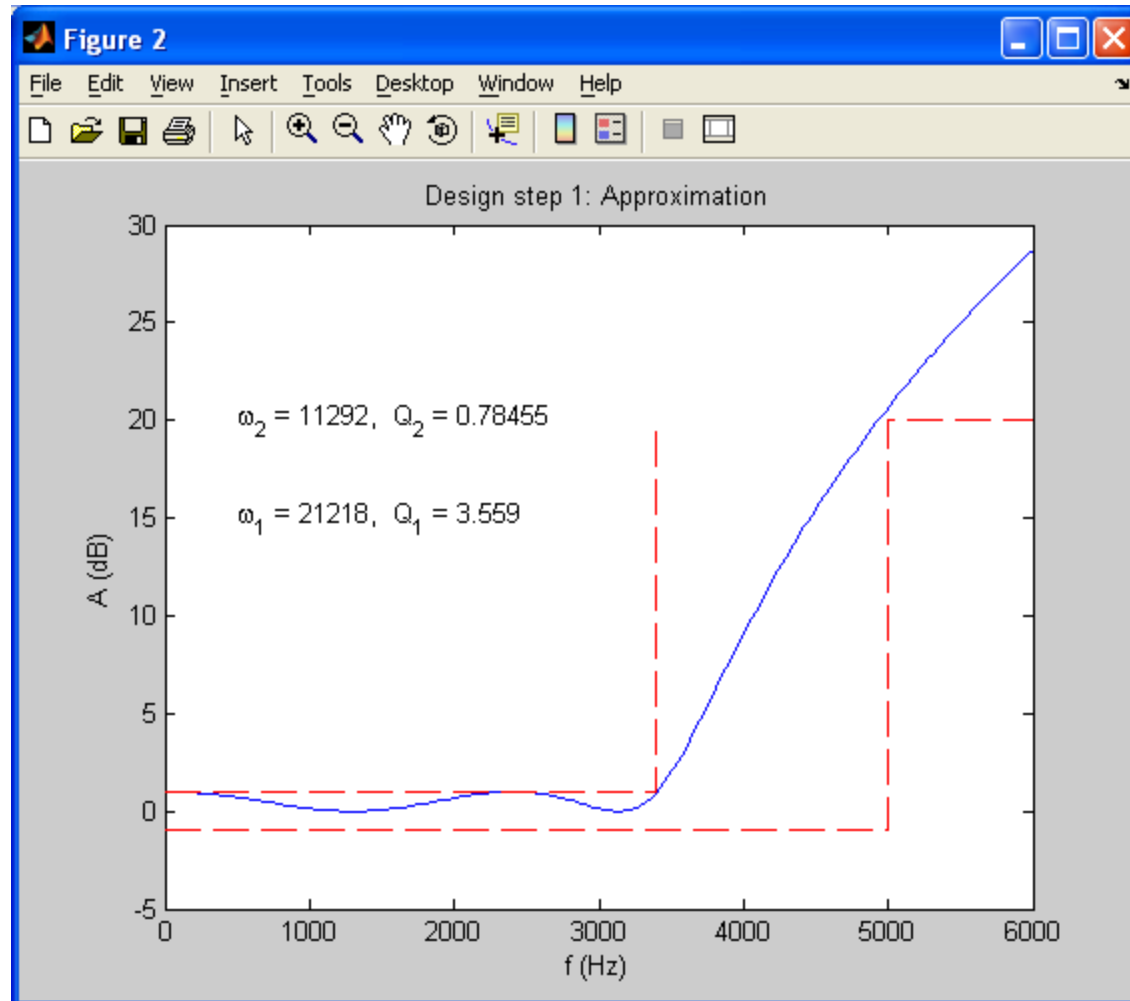
- Specifikacije
- 1: aproksimacija – izbor Čebiševljeve
- 2: realizacija – kaskada bikvada
- 3: analiza nesavršenosti – zaokruživanje vrednosti
- Ponavljanje projektovanja ako nije zadovoljen spek
  - 1: aproksimacija
  - 2: realizacija
  - 3: analiza nesavršenosti
- 4: implementacija
- MATLAB i dokumentacija

# Start sa specifikacijama



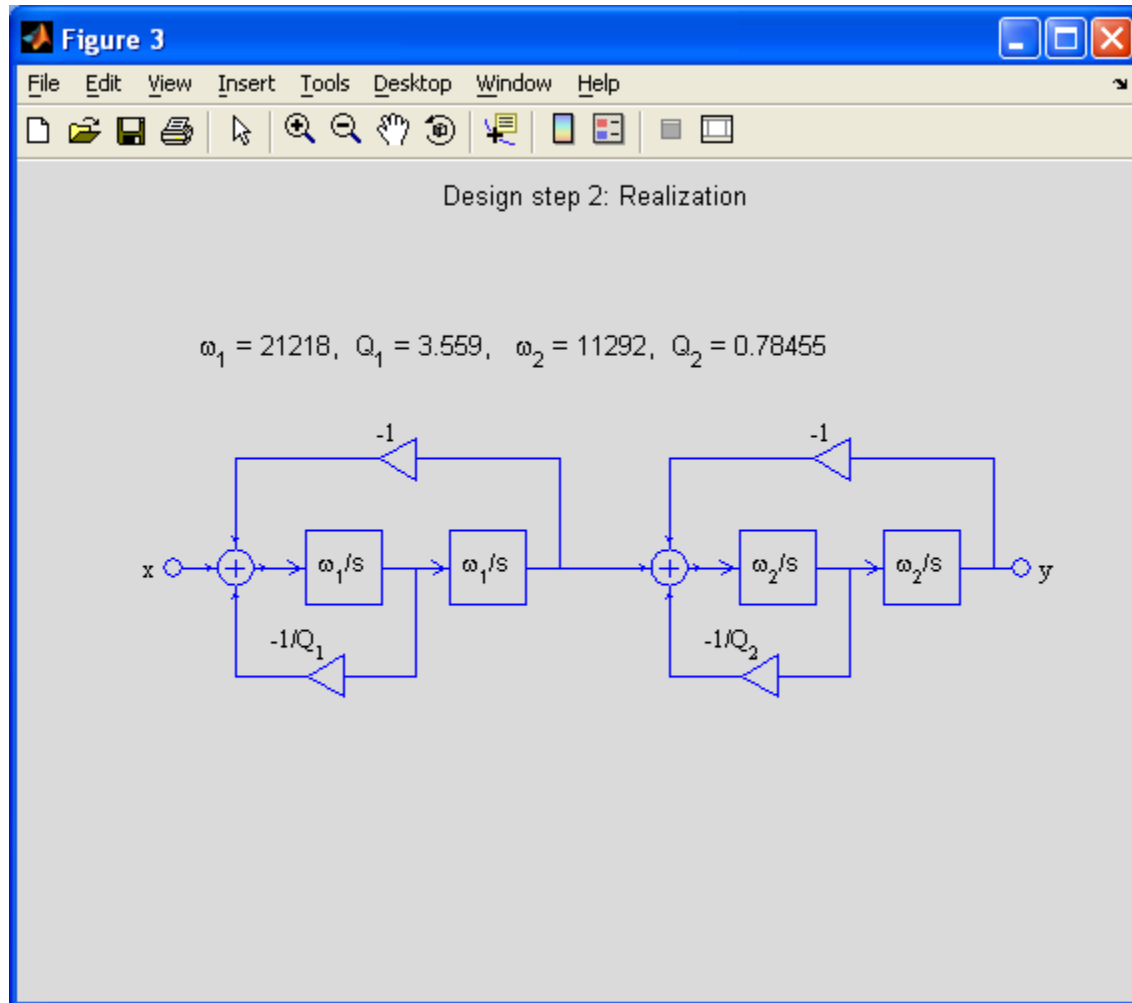
# 1: aproksimacija

## Izbor Čebiševljeve aproksimacije tip I

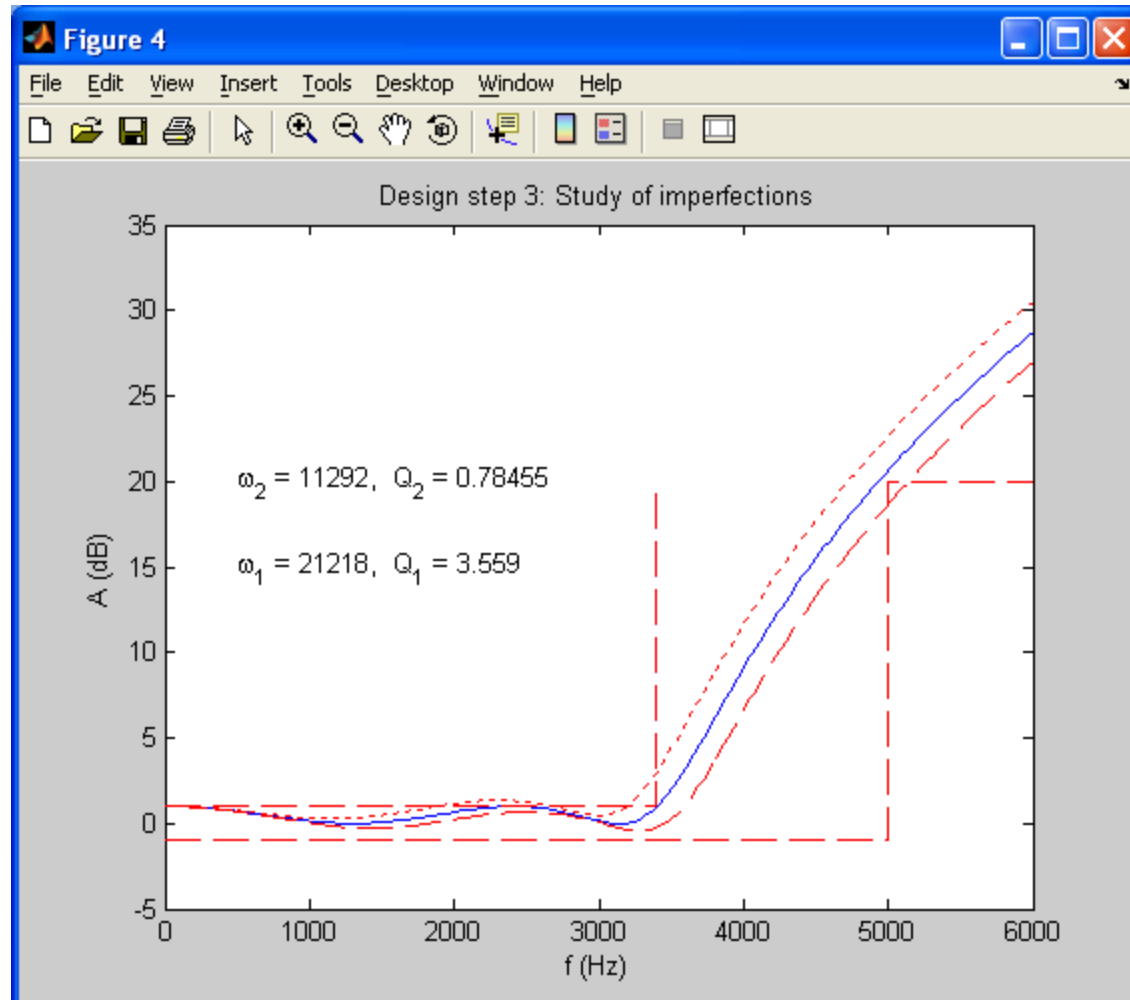


# 2: realizacija (sinteza)

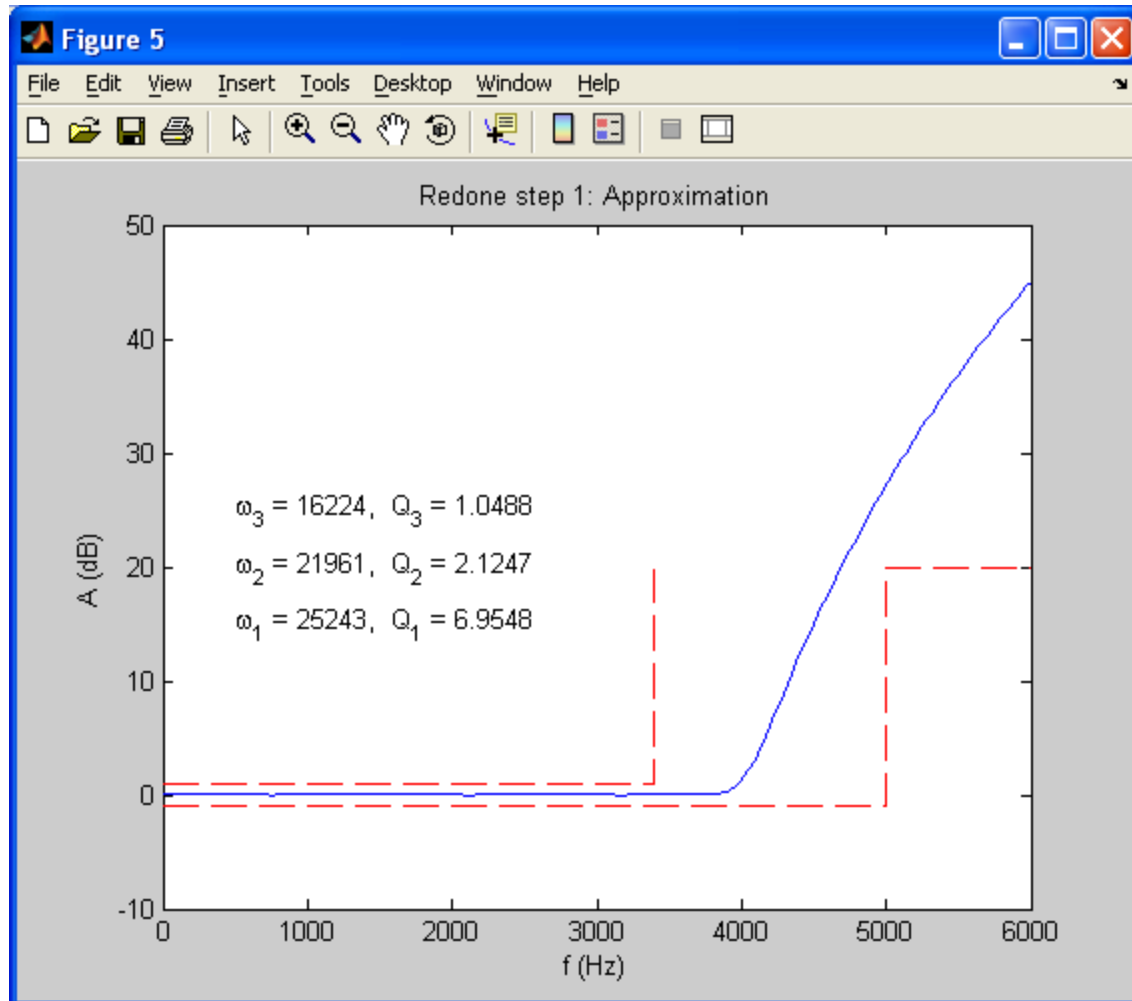
## Kaskada programabilnih sekcija drugog reda (biquads)



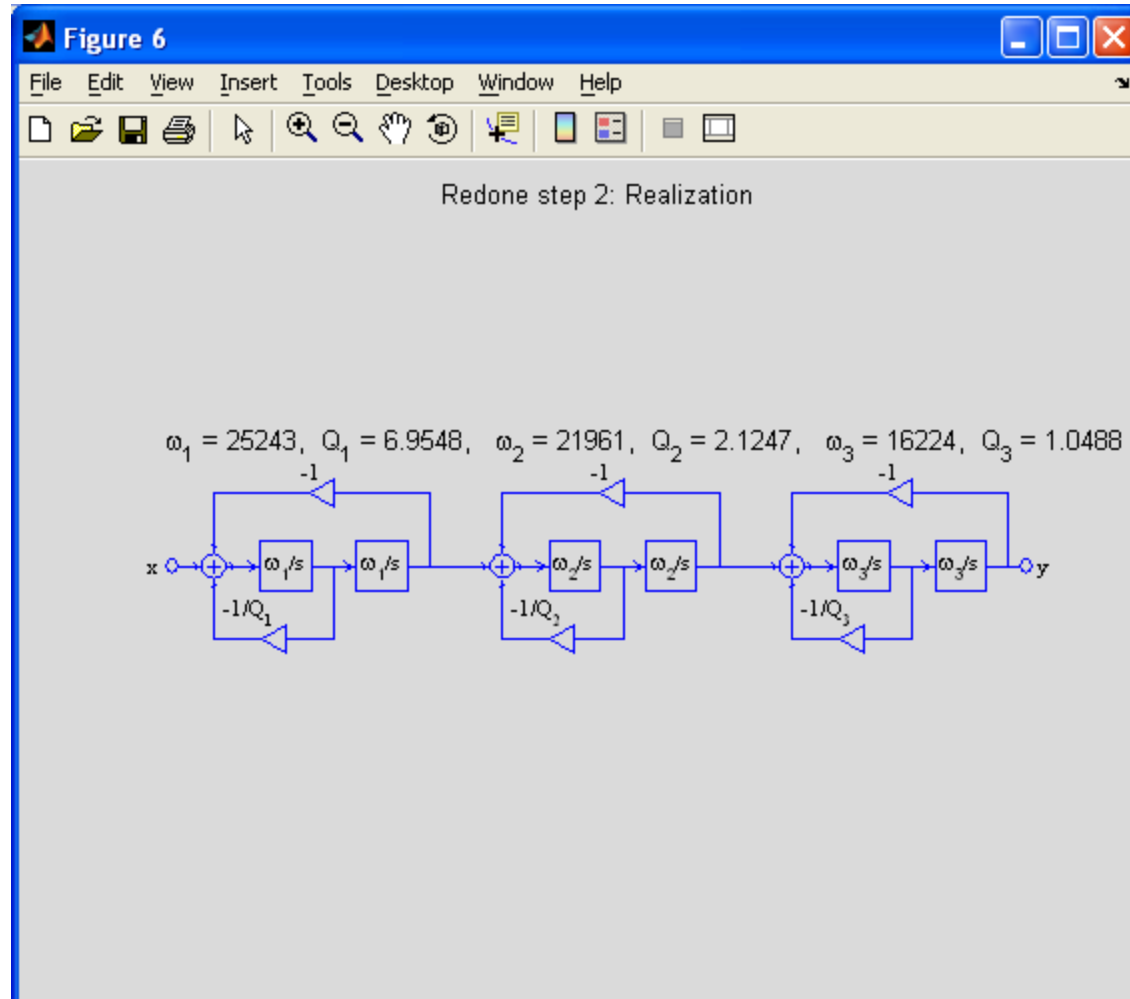
# 3: Analiza nesavršenosti analiza osetljivosti



# Ponovo 1: aproksimacija povećanje reda funkcije prenosa

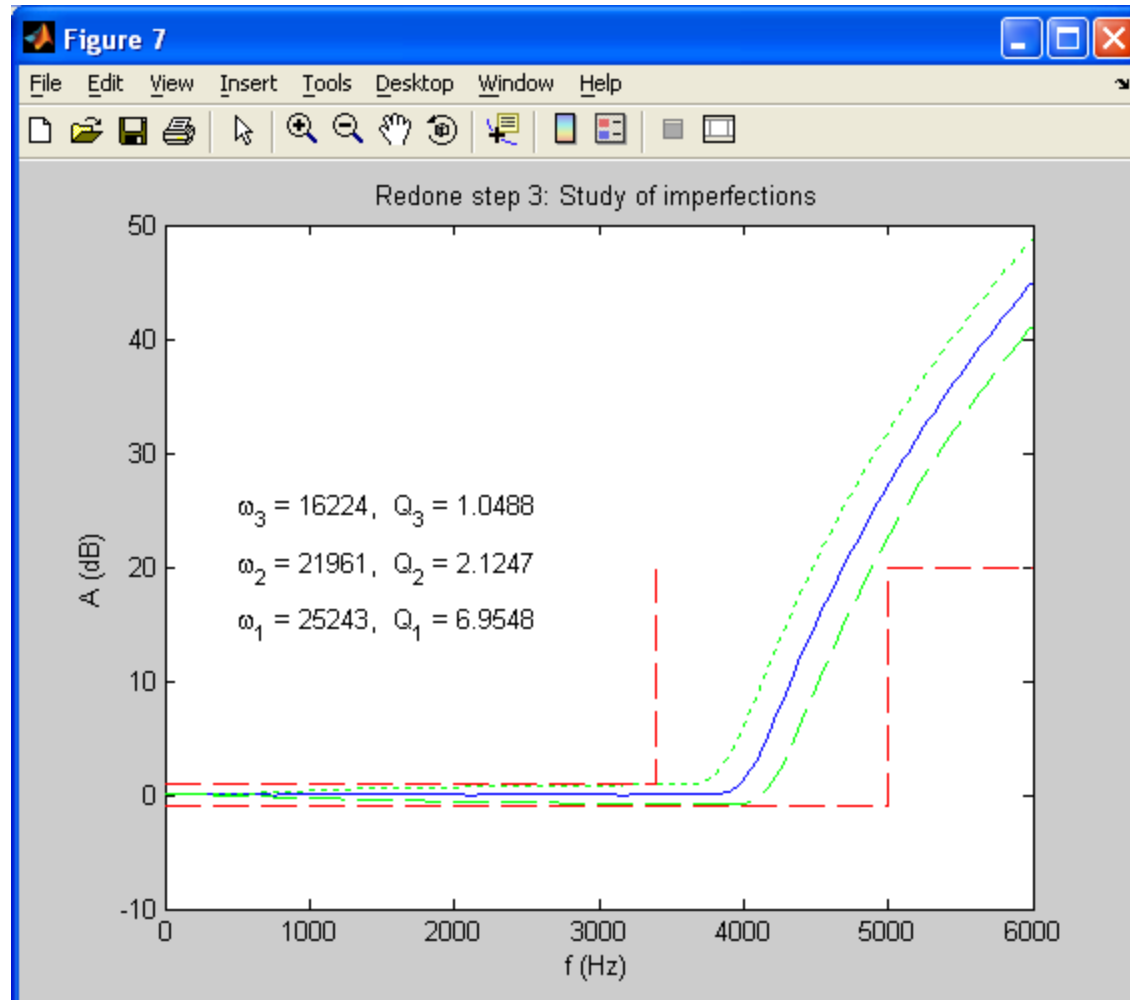


# Ponovo 2: realizacija



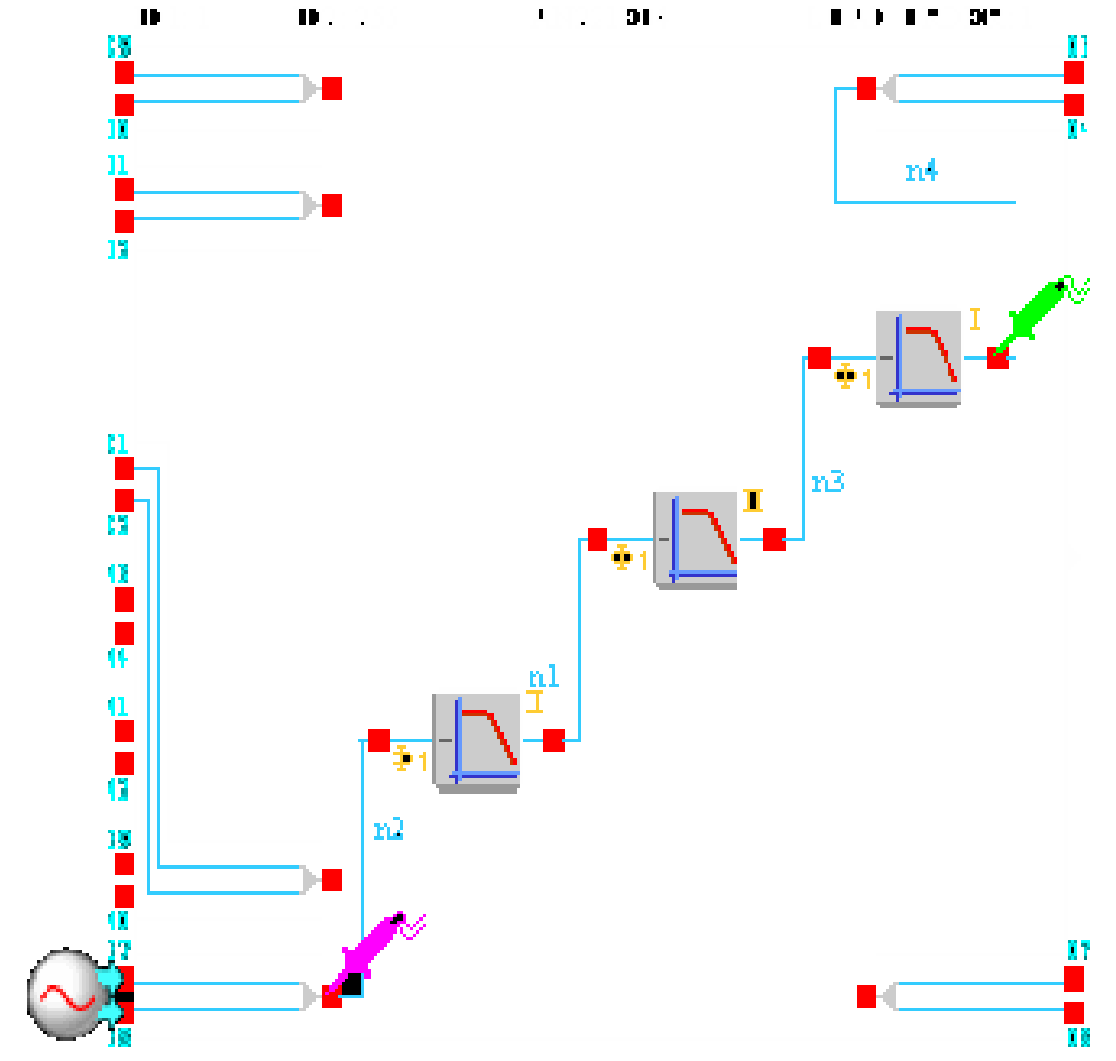


# Ponovo 3: analiza nesavršenosti

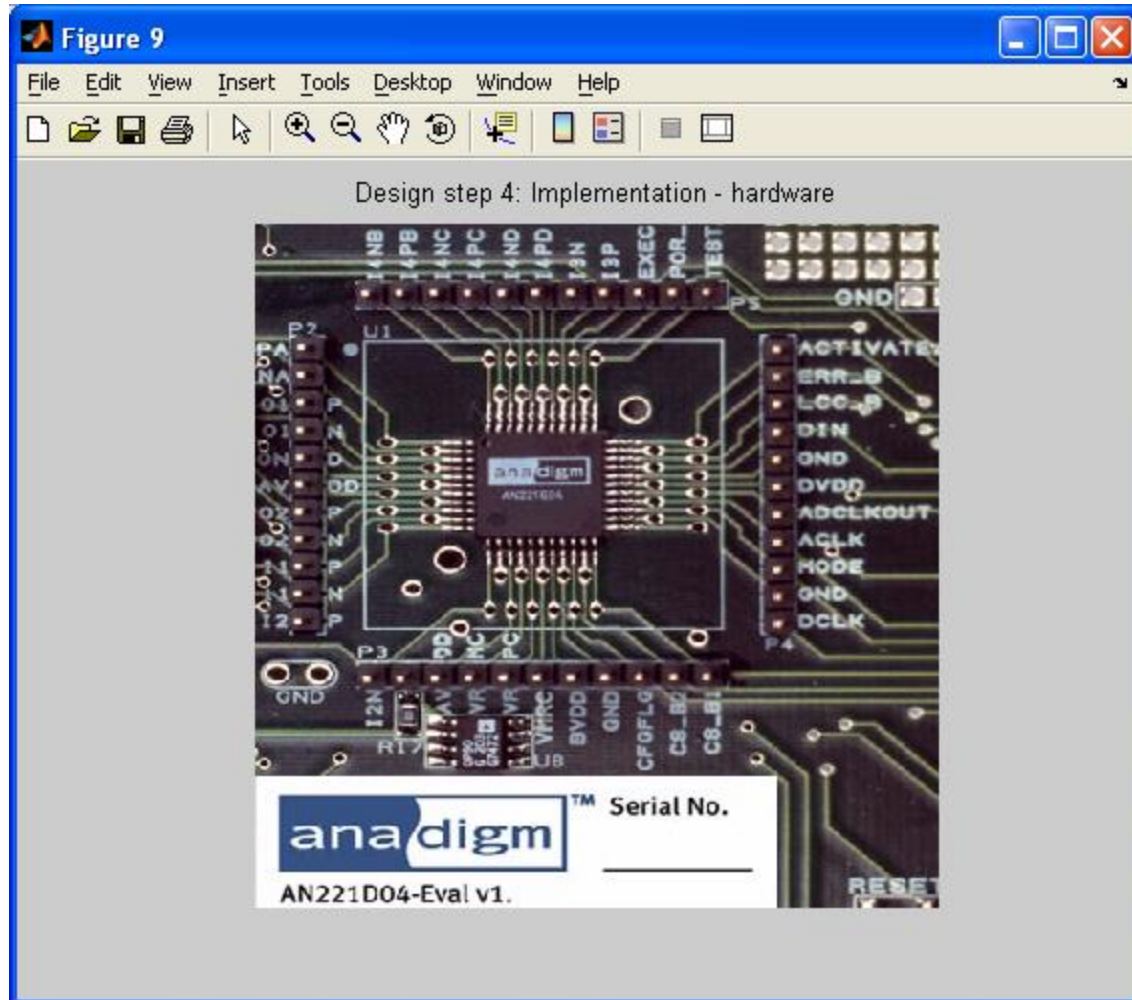


# 4: implementacija (1)

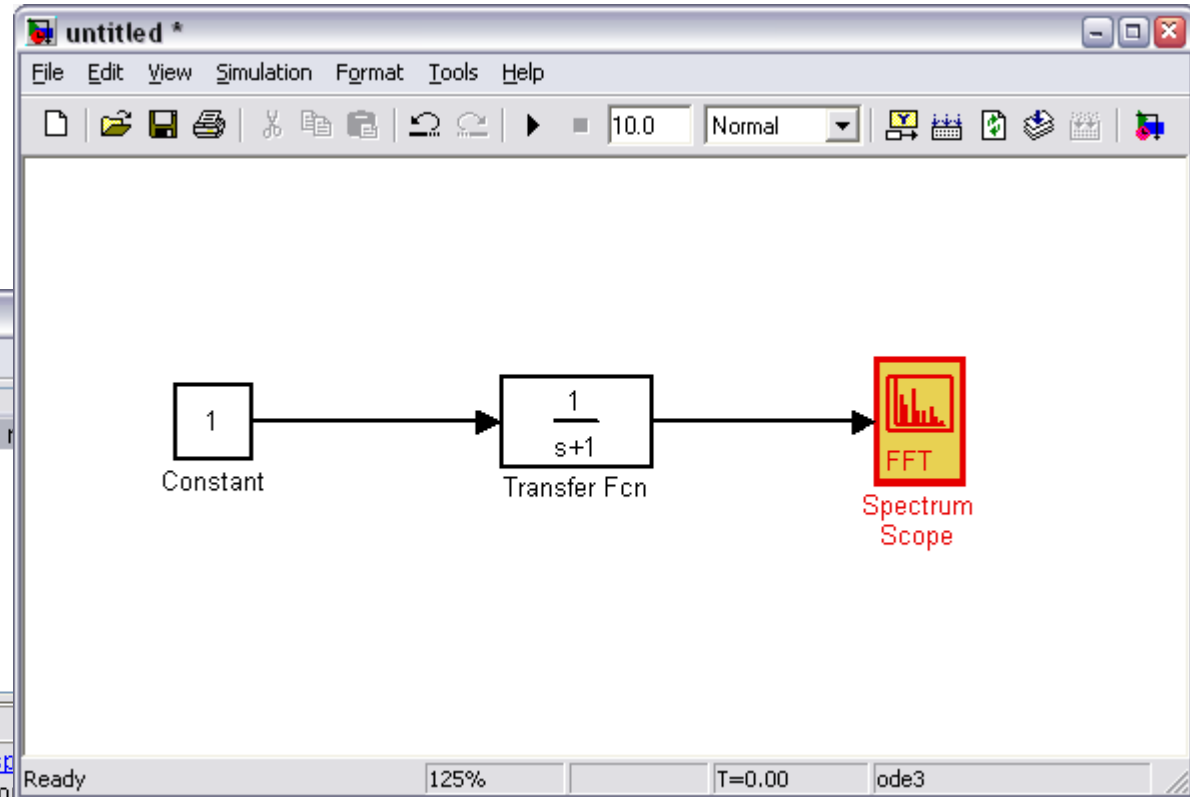
Design step 4: Implementation - block diagram



# 4: implementacija (2)



# Simulink ne podržava analizator spektra za kontinualne signale



untitled

View Font Size

Message	Source	Reported by	Summary
Block error	Frame Sco...	Simulink	Error evaluating r

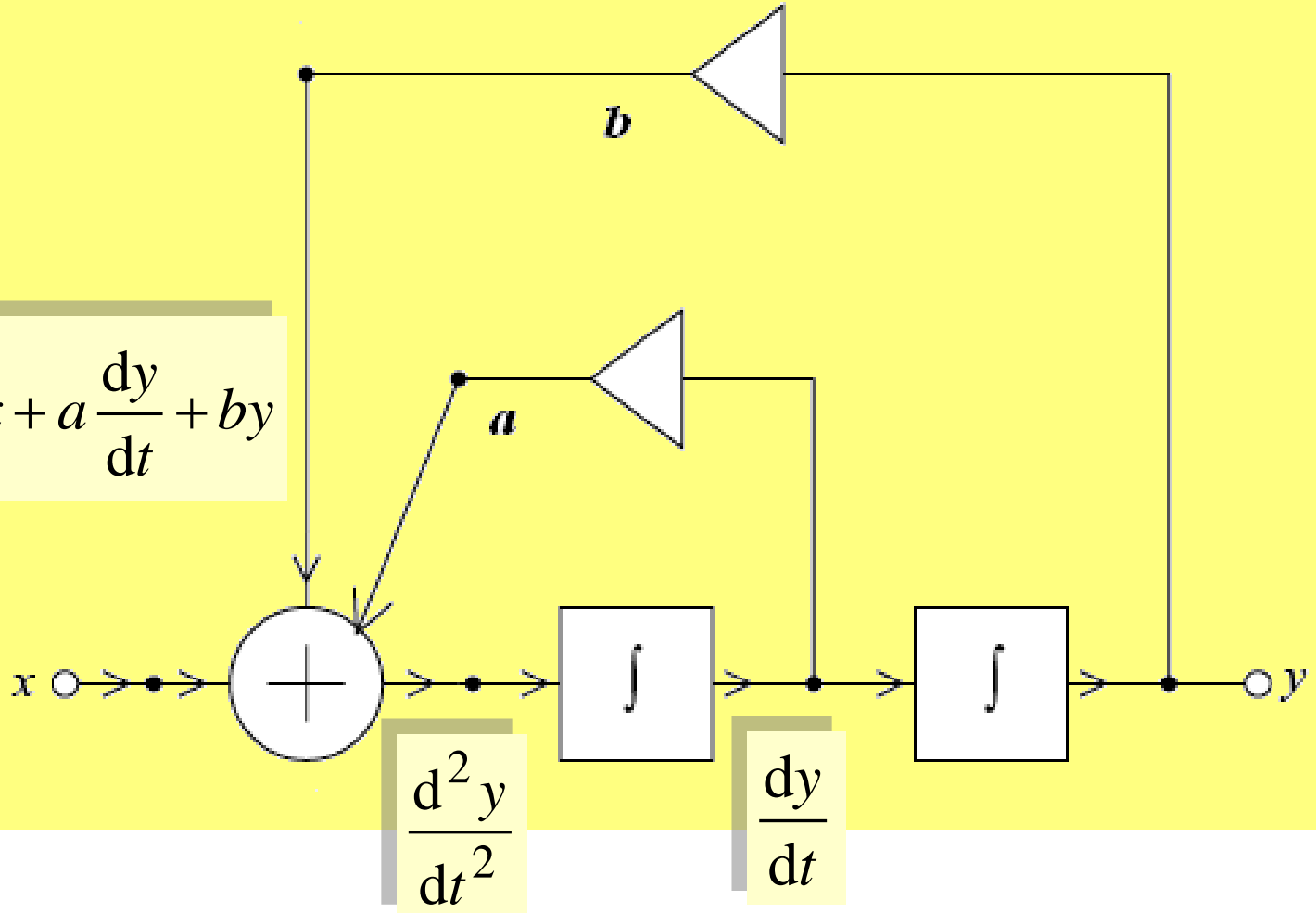
untitled/Spectrum Scope/Frame Scope

Error evaluating registered method 'Start' of M-S-Function '[sdspScope](#)'. Error using ==> sdspfscope2>Create\_or\_Restart\_Scope. Continuous-time inputs are not supported

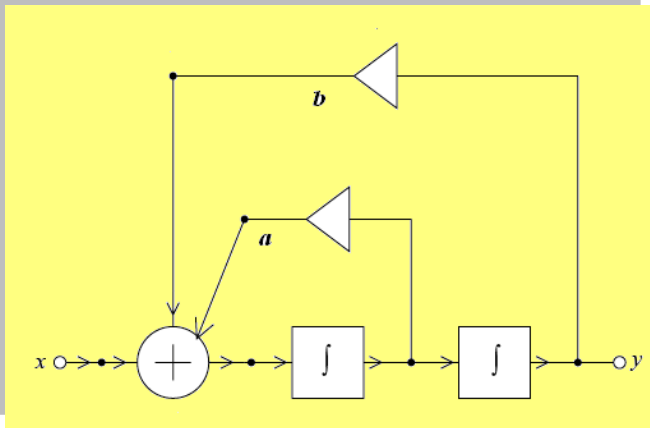
Open Help Close

# Kontinualni sistemi

$$\frac{d^2 y}{dt^2} = x + a \frac{dy}{dt} + by$$



# Primena Laplasove transformacije



$$\frac{d^2 y}{dt^2} = x + a \frac{dy}{dt} + by$$

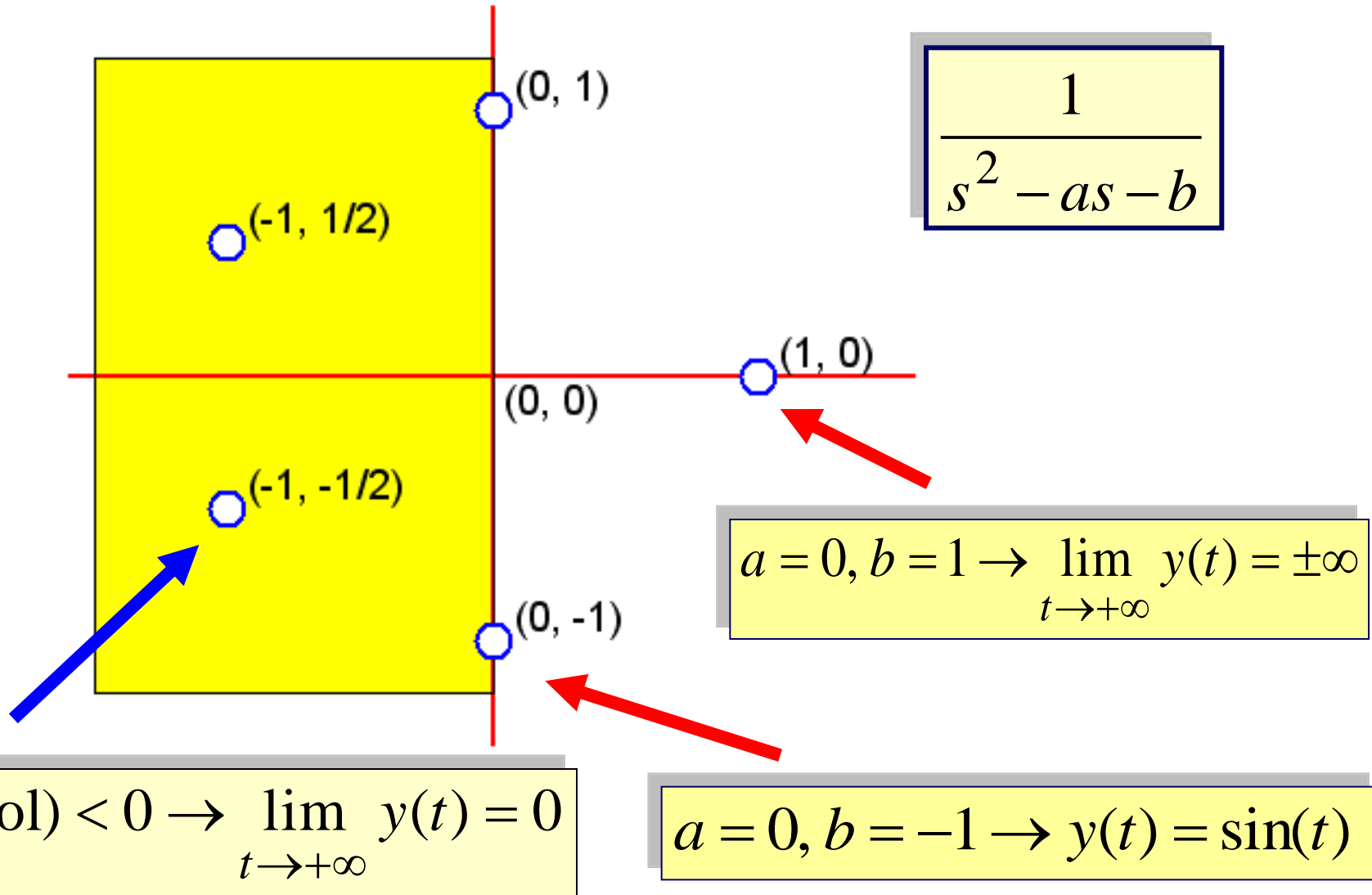
$$s^2 Y(s) = X(s) + a s Y(s) + b Y(s)$$

$$(s^2 - a s - b)Y(s) = X(s)$$

$$\frac{Y(s)}{X(s)} = \frac{1}{s^2 - a s - b}$$

Funkcija prenosa

# Polovi funkcije prenosa u s ravni



# Transformacije

- Laplasova transformacija impulsnog odziva

$$H(s) = \int_{-\infty}^{\infty} h(t)e^{-st} dt$$



# Funkcije prenosa

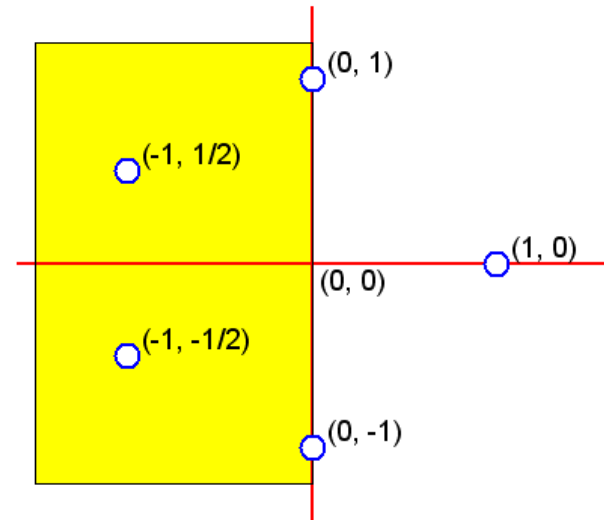
- Racionalna funkcija kompleksne frekvencije  $s = \delta + j\Omega$

$$H(s) = \frac{\sum_{k=0}^M c_k s^k}{\sum_{k=0}^N d_k s^k} = \frac{C(s)}{D(s)}$$

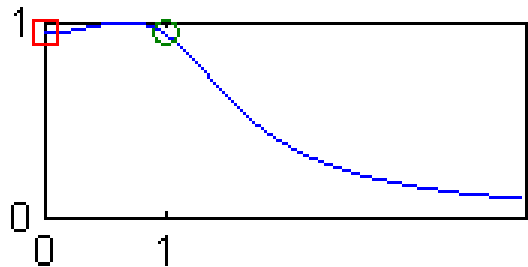
# Polovi funkcije prenosa

- Leva polovina kompleksne  $s$  ravni

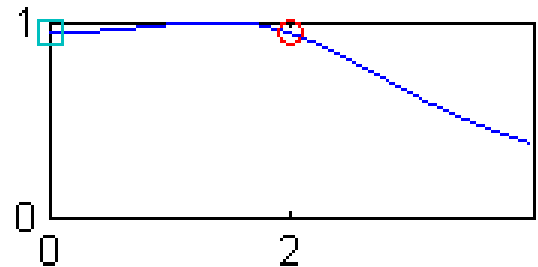
$$H(s) = \frac{C(s)}{D(s)}$$



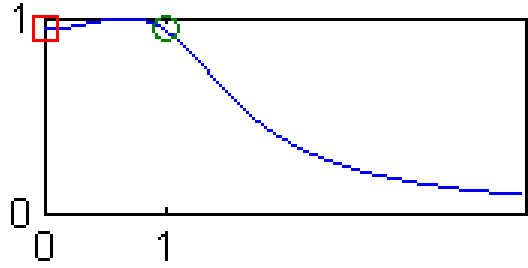
# Frekvencijske transformacije



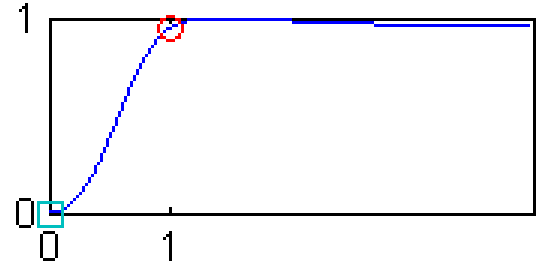
$$s \rightarrow \frac{s}{\Omega_0}$$



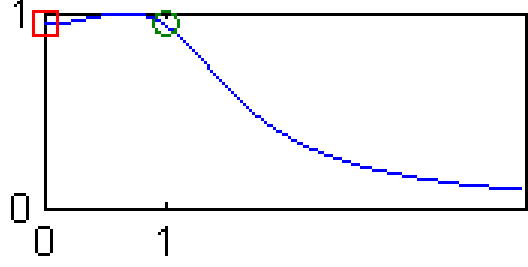
$$s \rightarrow j\Omega$$



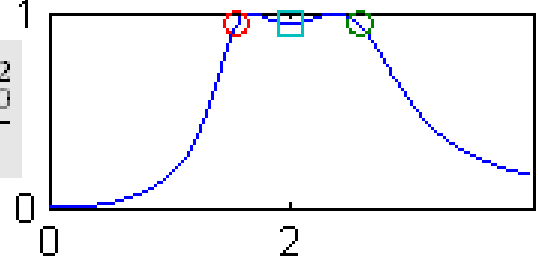
$$s \rightarrow \frac{1}{s}$$



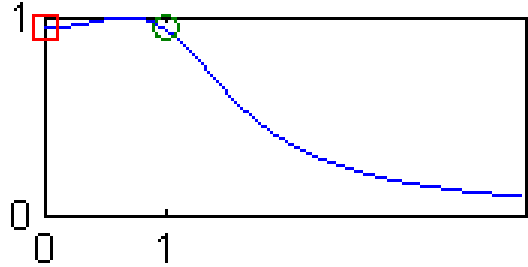
$$\Omega_0 = \sqrt{\Omega_{p1}\Omega_{p2}}$$



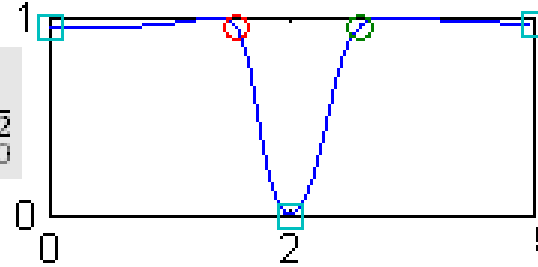
$$s \rightarrow \frac{s^2 + \Omega_0^2}{s}$$



$$\Omega_0 = \sqrt{\Omega_{a1}\Omega_{a2}}$$



$$s \rightarrow \frac{s}{s^2 + \Omega_0^2}$$



# Transformacije NF prototipa

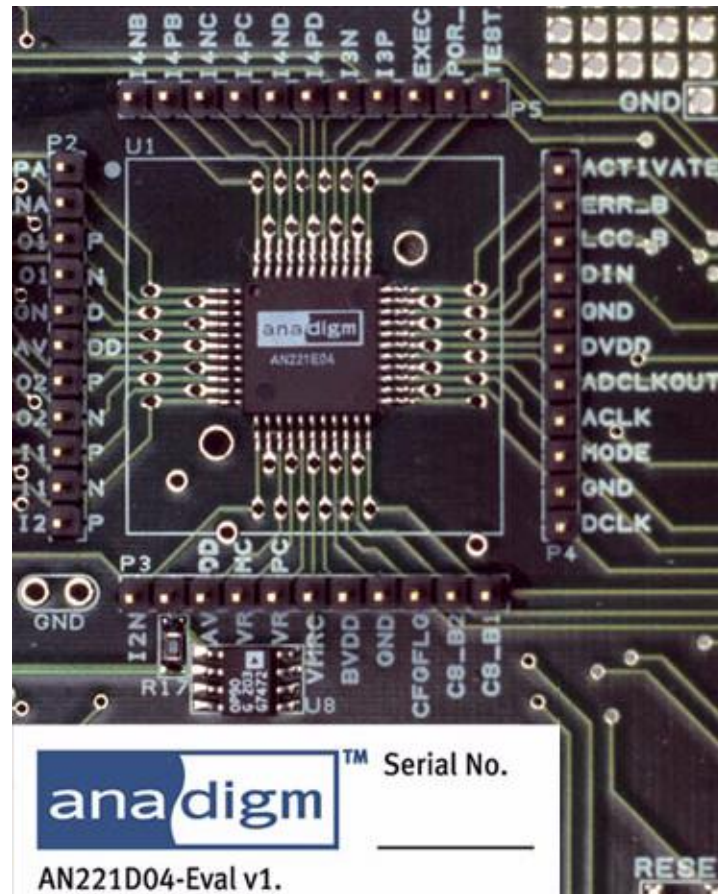
- Transformacija NF-NF prototip  $s \rightarrow s/\Omega_n$
- Transformacija VF-NF prototip  $s \rightarrow 1/s$
- Transformacija PO-NF prototip  
 $s \rightarrow (s^2 + \Omega_0^2)/s$
- Transformacija NO-NF prototip  
 $s \rightarrow s/(s^2 + \Omega_0^2)$

# Primer transformacije

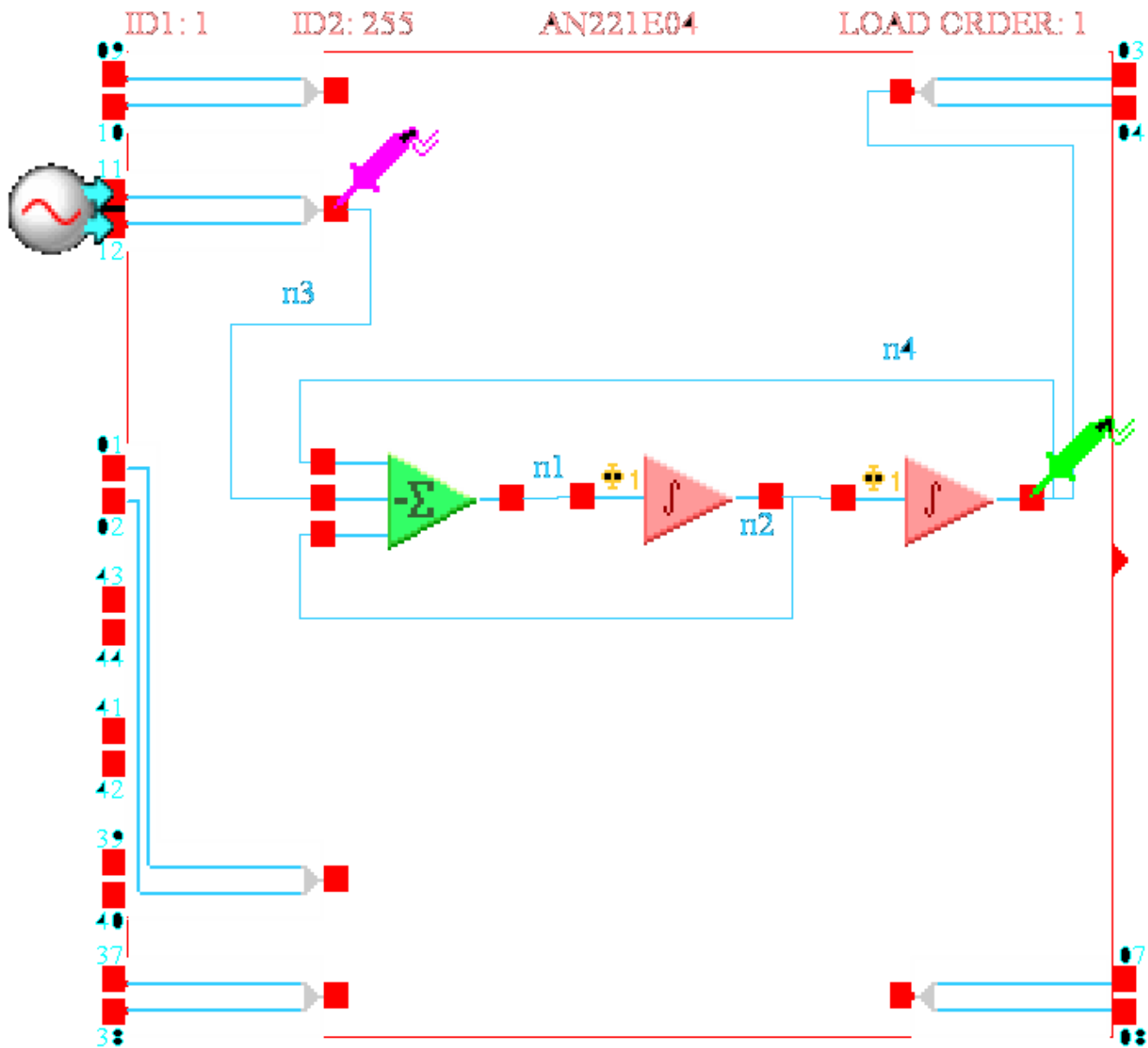
$$H_{\text{NF}} = \frac{1}{s^2 + 2s + 3} \Big|_{s \rightarrow \frac{s^2+1}{s}} \rightarrow H_{\text{PO}} = \frac{s^2}{s^4 + 2s^3 + 5s^2 + 2s + 3}$$

$H$  je racionalna funkcija

# Hardverska implementacija

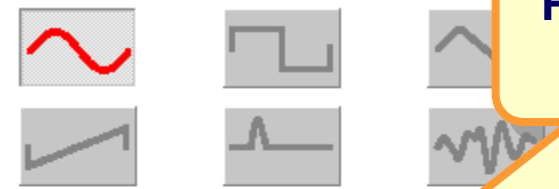


# Sistem sa integratorima



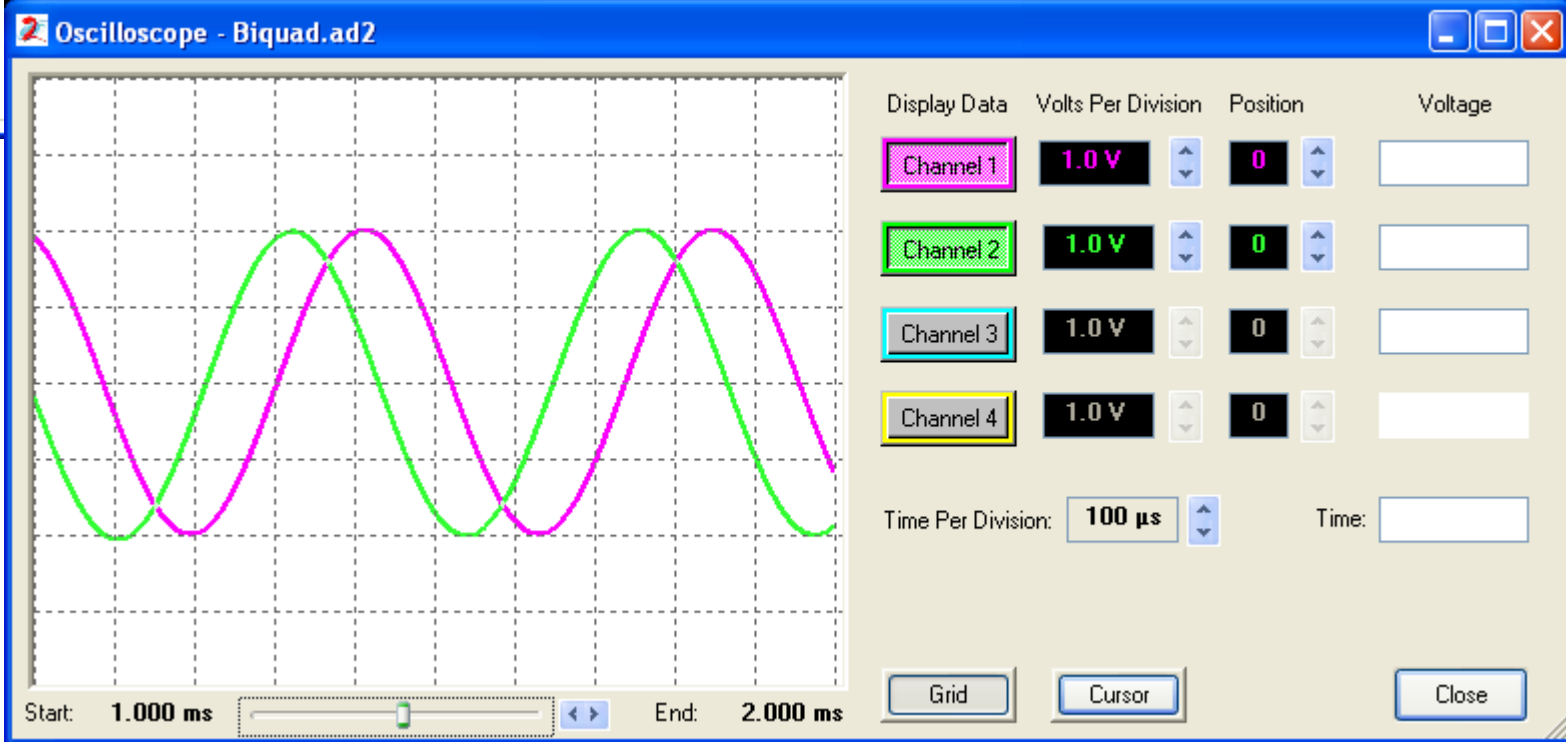
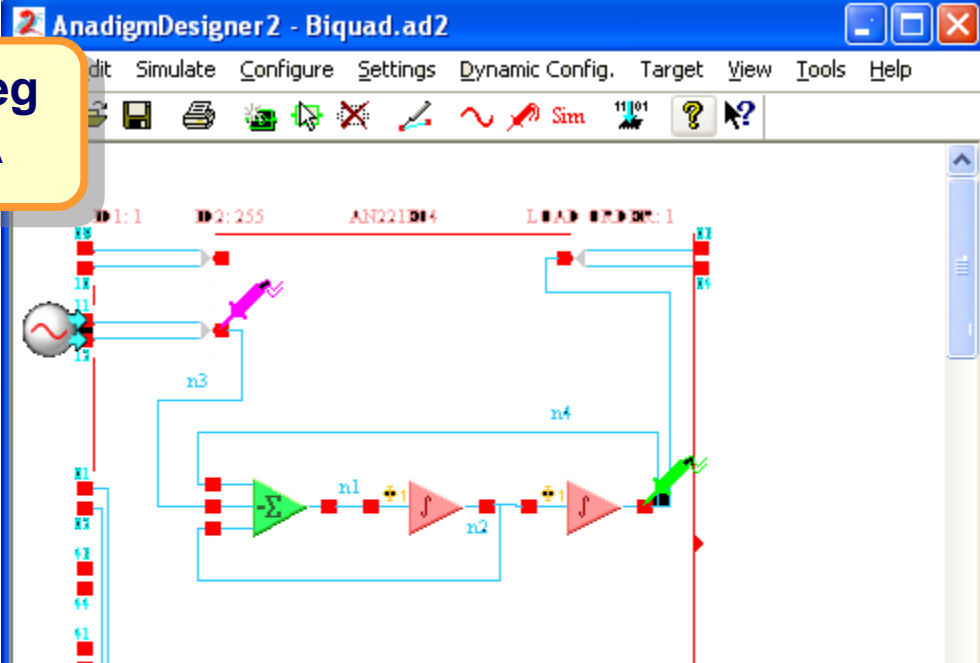
# Signal Generator Control

**Propusni opseg  
SIMULACIJA**



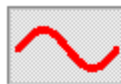
Output  
 Differential  Single Ended

Signal Data  
Peak Amplitude:  Volts  
Differential Offset:  Volts  
Frequency:  Hz  
Phase:  Degrees  
Common Mode Offset:  Volts





Signal Generator Control



Nepropusni opseg  
SIMULACIJA

Output

Differential  Single-ended

Signal Data

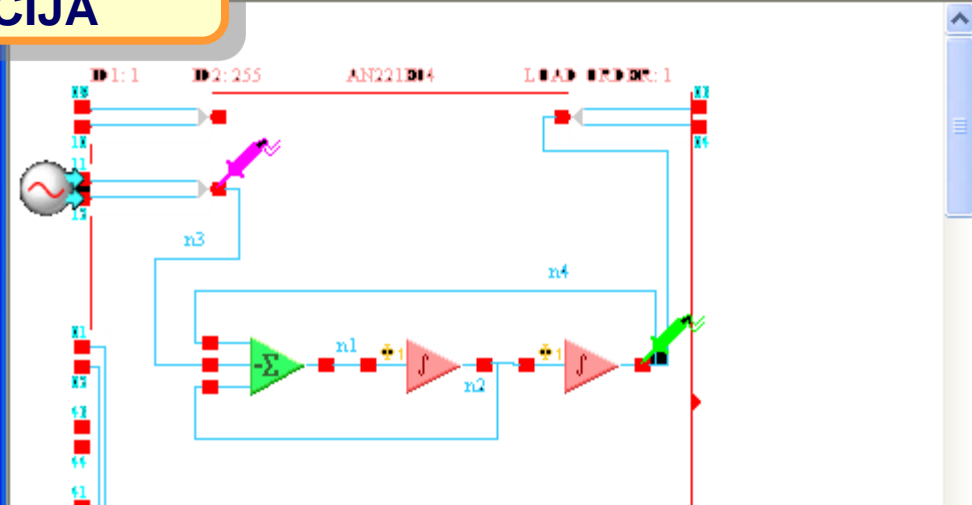
Peak Amplitude:  Volts

Differential Offset:  Volts

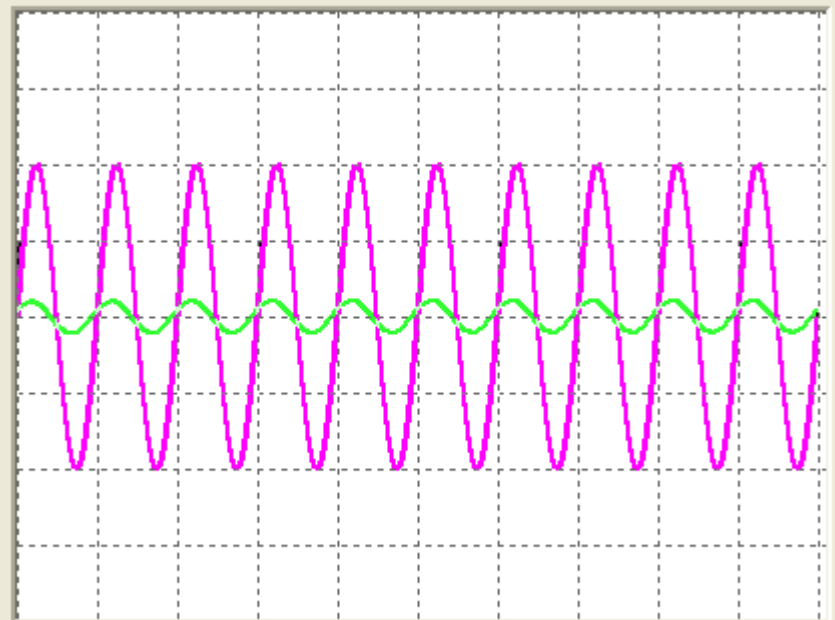
Frequency:  Hz

Phase:  Degrees

Common Mode Offset:  Volts



Oscilloscope - Biquad.ad2



Display Data	Volts Per Division	Position	Voltage
Channel 1	1.0 V	0	<input type="text"/>
Channel 2	1.0 V	0	<input type="text"/>
Channel 3	1.0 V	0	<input type="text"/>
Channel 4	1.0 V	0	<input type="text"/>

Time Per Division:  Time:

Grid Cursor Close

Start: 1.000 ms End: 2.000 ms

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- Earth Sciences
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#### Filter Design for Signal Processing Using MATLAB and Mathematica



Written for courses in design. Using mathematical and the advanced filter types of filters that can solve sample problems. (The

Companion Software: A set of MATLAB M-files is available. [Retrieve companion software](#)

### MATLAB & Simulink Based Books- Signal Processing

#### Multirate Systems: Design & Applications



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#### Filter Design for Signal Processing Using MATLAB and Mathematica



Miroslav D. Lutovac, University of Belgrade

Dejan V. Tosic, University of Belgrade

Brian L. Evans, University of Texas at Austin

[Publishing House of Electronics Industry](#), 2004

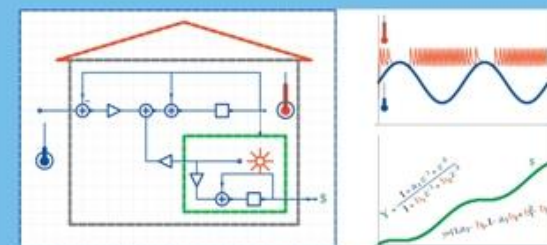
Tel: +86-10-6821-4070

ISBN: 7-5053-8710-3

Language: Chinese

Written for courses in design. Using mathematical and the advanced filter types of filters that can solve sample problems. (The

Miroslav Lutovac • Dejan Tošić



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